

Optimization in the Position of Tail Engine on the Fuselage for Drag Reduction

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ABSTRACT: The main purpose of our project is to study the boundary layer in the air flow over the fuselage and how boundary layer is affected due to introduction of tail engine. For the following purpose we considered a cylindrical pipe as fuselage and used propeller as the tail engine. We tested our model in the wind tunnel at different positions (10cm, 20cm, 30cm from rear edge of fuselage), different velocities of wind tunnel (6.2m/s, 9m/s, 12.4m/s) and different motor rpm (rpm=0, rpm=175, rpm=350) and concluded our results whether the boundary layer shifts or not by placing tail engine. If it shifts, at what position it will be most suitable to place the engine. We noted height in manometer and obtained pressure and normal reaction force. After that, we calculated drag and found without engine mounting, there will be more drag but after placing engine at the rear of the fuselage we concluded that the skin friction drag is reduced substantially. From above experimental result we concluded that, the drag is gradually decreasing as we are on increasing rpm of mounted motor but when air flow velocity is increases, some drag also increases due to shift of air flow from laminar to the turbulence.

KEYWORDS: Boundary Layer, Fuselage, Rear Engine, Wind Turbine, Throttle.

I. INTRODUCTION

A tail engine plane is pusher type plane in which engine is mounted over the rear of fuselage in the vertical stabilizer. The primary purpose of the tail plane is to suck air over the fuselage in order to reduce drag over fuselage and keep the flow smooth. Tail engine sucks the air over the fuselage, than the laminar boundary layer separation shift towards the tail. The air molecules at the surface of a fuselage are effectively stationary. Smooth flow known as laminar flow, the velocity of the air increases steadily as measurements are taken further away from the surface. However the smooth flow is often disturbed by the boundary layer breaking away from the surface and creating a low pressure region immediately behind the airfoil. This low pressure region results in increased overall drag. Attempts have been made over the years to delay the onset of this flow separation by careful design and smooth surfaces. As we know that low pressure region is created immediately after the airfoil, overall drag increases over fuselage. To reduce this drag, an engine is placed at the rear of fuselage. This engine is mounted in the vertical stabilizer. The inlet air from this engine is passed to the compressor through the S-shaped duct and produces thrust. Due to this engine, the flow will be attached to the fuselage delaying the breaking of flow. We tested our model at different conditions.

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Wind tunnel speed	Motor rpm	Position from rear of fuselage
6.2m/s	0	10cm
9m/s	175	20cm
12.4m/s	350	30cm

Robert B. Brown¹, we observed that A mid wing aircraft employs a unique configuration for mounting 3 high bypass turbofan engines. The exhaust from the each of engine is directed by 2 nozzles. The left engine (port) is mounted on the in board position of the left wing adjacent to the fuselage. Similarly right engine is mounted in the starboard side. Andrew J. Comb²The third engine is mounted above the aft position of the fuselage and is fixed to the vertical stabilizer. The air inlet of this engine is positioned forwardly of the leading edge of the vertical stabilizer while reversely portion comprising the exhaust nozzle opens to the left and right side of the vertical stabilizer.

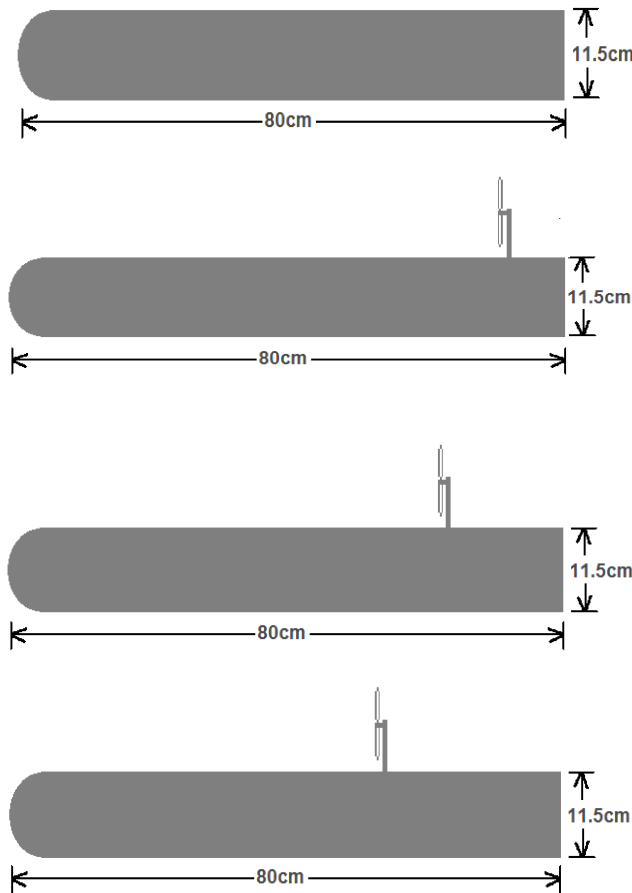


Fig 1 Positioning of Engine over the fuselage

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As we know that low pressure region is created immediately after the airfoil, overall drag increases over fuselage. To reduce this drag, an engine is placed at the rear of fuselage. This engine is mounted in the vertical stabilizer. The inlet air from this engine is passed to the compressor through the S-shaped duct and produces thrust. Due to this engine, the flow will be attached to the fuselage delaying the breaking of flow.

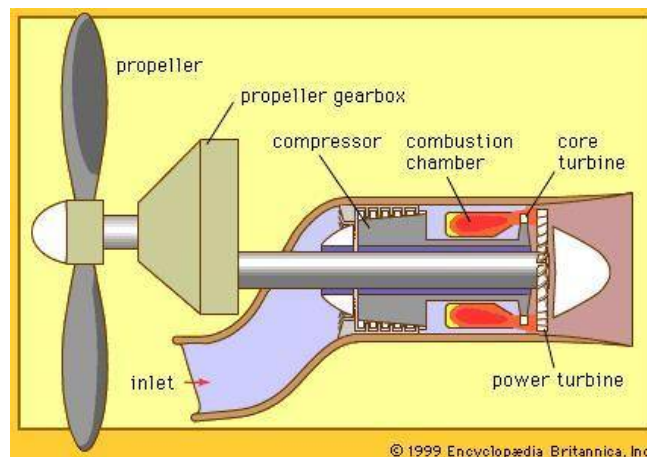


Fig. – 2 Conceptual Design

II. RESEARCH METHDOLOGY

Model Specification

- 1) Diameter of the propeller = 5inch
- 2) Pitch of the propeller = 3inch
- 3) Motor speed = 1400rpm
- 4) 1400kV brushless motor
- 5) Fuselage:
 - a. cylindrical shape
 - b. Length = 32inch
 - c. Diameter = 4.5inch
- 6) Wind tunnel:
 - a).Suction type
 - b).Dimension of test section = 100x30x30 cm
 - c).Subsonic wind tunnel

A hollow pipe of diameter 4.5inch is taken for the fuselage model having length of 30inch. One side of the pipe is packed using metal sheet by welding it at one end of the pipe. The extra material of the welding is removed using grinder to keep the surface of fuselage smooth. A rectangular section is cut at the rear of the fuselage to introduce the battery setup. 3 other cuts are given to place the propeller which is mounted on a stand. These cuts are made at equal interval of 10cm. Each cut is provided with a hole for the wiring of battery. 6 holes are made starting from 40cm from rear at equal interval of 1.5inch. Each hole is given hollow spoke from inside of the fuselage for the pressure reading

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during experiment. Spokes are attached by gas welding. Two sections are cut below the fuselage to attach these spokes with the pressure tubes. A stand is provided to place the engine over fuselage. Wind tunnel is tested if it working properly. Glass of the test section of the wind tunnel is removed to place the fuselage in test section. Pressure tubes of the model are connected with the manometer pressure tubes. Glass of the test section is fitted again and all the openings in wind tunnel are packed. Wind tunnel speed is changed using knob associated with the control panel and speed is calculated using anemometer. Battery, necessary wires connections and the engine mounting are done through the removable glass of test section. Safety precautions have been considered. Velocity of air in the wind tunnel is set at 6.2m/s, 9m/s, 12.4m/s. Then model is placed in the wind tunnel test section. Pressure tubes of the model are connected to the manometer pressure tubes. Pressure over the model is noted without mounting engine at above mentioned 3 different throttles.

Engine is mounted at position 1 (30cm from rear of fuselage) and pressure is noted at above mentioned throttles with 3 different motor rpm (0 rpm, 175rpm, 350rpm). Now, engine is mounted at position 2 (20cm from rear of fuselage) and pressure is noted at above mentioned throttles with 3 different motor rpm mentioned above. Finally, engine is mounted at position 3 (10cm from rear of fuselage) and pressure is noted at above mentioned throttles with 3 different motor rpm mentioned above.

$$\text{Pressure from manometer} = \rho * g * H$$

$$C_p = \frac{P - P_s}{P_o - P_s} = \frac{\rho g \Delta H}{0.7239}$$

$$(P_o - P_s = 0.7239 \text{ Pa})$$

$$\Delta H = H - H_s$$

Where H is the manometer height for dynamic pressure

H_s is the manometer height for static pressure

P (Density of water) = 1000 kg/m³

g (acceleration due to gravity) = 9.81 m/sec²

ΔP (Change in pressure) = $\rho g \Delta H$

Normal reaction (N) = $\Delta P \times A$

Drag = μN (Frictional force)

μ (surface friction coefficient) = 0.21 (for cast iron)

Area around pressure holes = $\pi r^2 h = 3.581 \times 10^{-4} \text{ m}^2$

Let us consider an example for our analytical calculations.

Calculations for pressure pt. 1 (without engine mounting):

Manometer rise H = 21.5cm

Manometer rise for statics pressure = 21.3cm

$$\Delta H = H - H_s = 0.2 \text{ cm}$$

$$C_p = \frac{P - P_s}{P_o - P_s} = \frac{\rho g \Delta H}{0.7239} = \frac{1.2245 * 9.81 * 0.20}{0.7239} = 1.8217$$

$$\Delta P = P - P_s = \rho g \Delta H = 2.4024 \text{ Pa}$$

$$N = \Delta P \times A = 2.4024 \times 3.581 \times 10^{-4}$$

$$= 8.6302 \times 10^{-6} \text{ N} = 8.6302 \times 10^{-4} \text{ N}$$

$$D = \mu N = 0.21 \times 8.6302 = 1.8123 \times 10^{-4} \text{ N}$$

III. EXPERIMENTAL SET-UP

Specifications & dimensions:

We considered the dimensions of our model (1/50th) times the dimensions of Boeing 727-200. By using this scale we calculated length of our model 32 inch and diameter of model 4.5 inch. We used a propeller of diameter 5 inch

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and having pitch 3inch as our tail engine. Speed of the motor with which the propeller is being rotated is 1400rpm. The motor is a brushless type DC motor of 1400kV. To supply the necessary power, we used a battery of 2200mAh. A 30A Electronic Speed Controller (ESC) is used to control the speed of motor. We tested our model in wind tunnel, which is a subsonic open and suction type wind tunnel. Dimension of the test section of the wind tunnel is 100cmx30cmx30cm. We constructed our model in such a way that it can be placed easily in this test section. The blower fan of wind tunnel is 5 blades Aluminium dia cast fan. Motor of wind tunnel is of 3 HP, AC induction motor of speed 2880rpm of 440V working on 15A. Tunnel of the wind tunnel is of length 4.2m approx. and having contraction ratio 9:1

Construction:

For the construction of model we used a hollow pipe (Cast iron) of length 80cm and diameter 11.5cm. One end of the fuselage is welded with thin metal sheet in spherical shape and the other end kept open for battery setup. A cut section of dimension 10x5cm is provided lower side of the model with the help of the grinder. Similarly three cut section are provided at the upper surface of the model at distance of 10cm, 20cm, and 30cm from rear of model for motor assembly. Three holes are drilled behind cut section for wiring purpose. Surface finishing is obtained by using grinder for smooth flow. Model is painted with the Spray paint to avoid brush strokes and to have great smoothness. Sharp edge of rear of fuselage is grinded to ensure proper safety and to reach the required dimension for the model.

Pressure tube assembly:

In order to provide pressure tube in model, six holes are drilled on the upper surface of model. These holes are provided hollow spokes (volleyball air inlet pipe) which are welded with gas welding from inner side of model. These spokes are connected to the pressure pipes. These pipes are carried out from the cut section provided at the bottom surface of the model.

Motor Engine Mounting:

Motor is fixed to stand with the help of four screw. The propeller is mounted on motor shaft with hub screw. Holes are provided behind each cut section for mounting engine stand. The entire assembly of propeller, motor and stand is mounted on those cut section of the fuselage with the help of nut and bolt.

Procedure:

Our model is placed inside of the subsonic suction type wind tunnel. Glass of the test section of the wind tunnel is removed to place the fuselage in test section. Pressure tubes of the model are connected with the manometer pressure tubes. Glass of the test section is fitted again and all the openings in wind tunnel are packed. Wind tunnel speed is changed using knob associated with the control panel and speed is calculated using anemometer. Battery, necessary wires connections and the engine mounting are done through the removable glass of test section. Safety precautions have been considered.

Velocity of air in the wind tunnel is set at 6.2m/s, 9m/s, 12.4m/s. Then model is placed in the wind tunnel test section. Pressure tubes of the model are connected to the manometer pressure tubes. Pressure over the model is noted without mounting engine at above mentioned 3 different throttles. Engine is mounted at position 1 (30cm from rear of fuselage) and pressure is noted at above mentioned throttles with 3 different motor rpm (0 rpm, 175rpm, 350rpm). Now, engine is mounted at position 2 (20cm from rear of fuselage) and pressure is noted at above mentioned throttles with 3 different motor rpm mentioned above. Finally, engine is mounted at position 3 (10cm from rear of fuselage) and pressure is noted at above mention throttles with 3 different motor rpm mentioned above.

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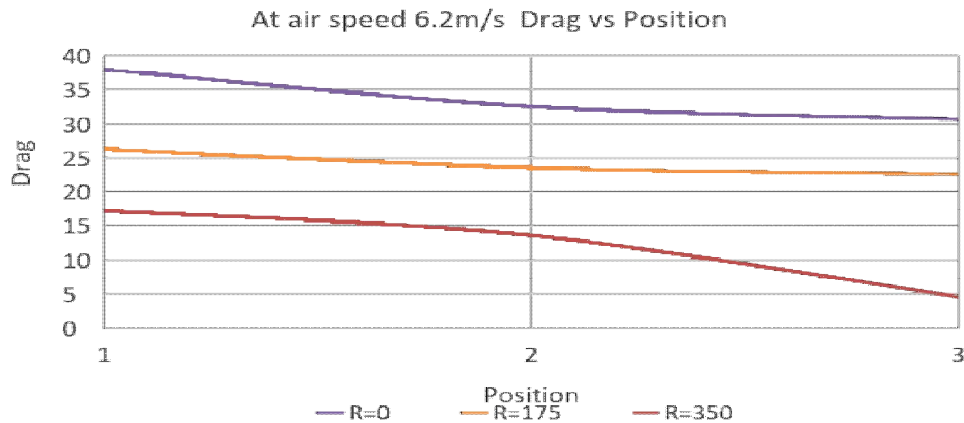
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IV. RESULTS AND DISCUSSION

At air speed 6.2m/s Drag vs Position (Where Engine Motor RPM is throttle of wind tunnel)

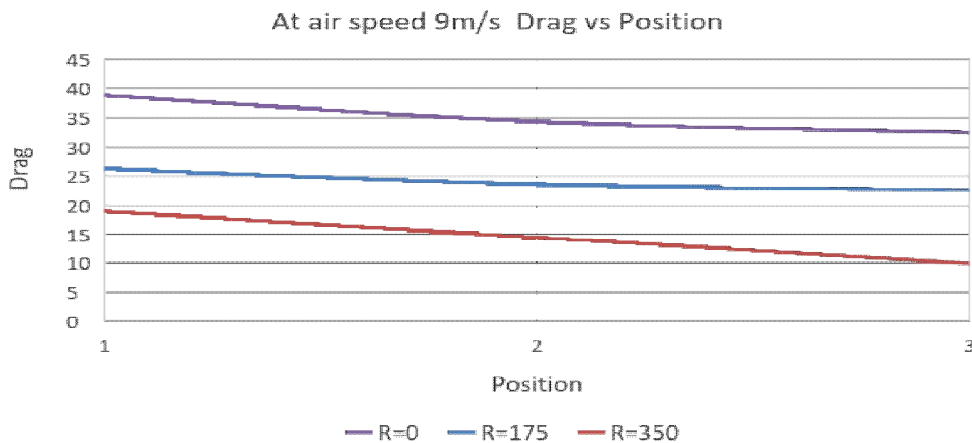
Engine position	R=0	R=175	R=350
1	37.939	26.205	17.708
2	32.521	23.497	13.57
3	30.717	22.596	4.533



Graph - 1 (Drag vs Position at 6.2 m/s)

At air speed 9m/s Drag vs Position (Where Engine Motor RPM is throttle of wind tunnel)

Engine position	R=0	R=175	R=350
1	38.842	26.205	18.986
2	34.327	23.497	14.472
3	32.521	22.596	9.961



Graph - 2(Drag vs Position at 9 m/s)

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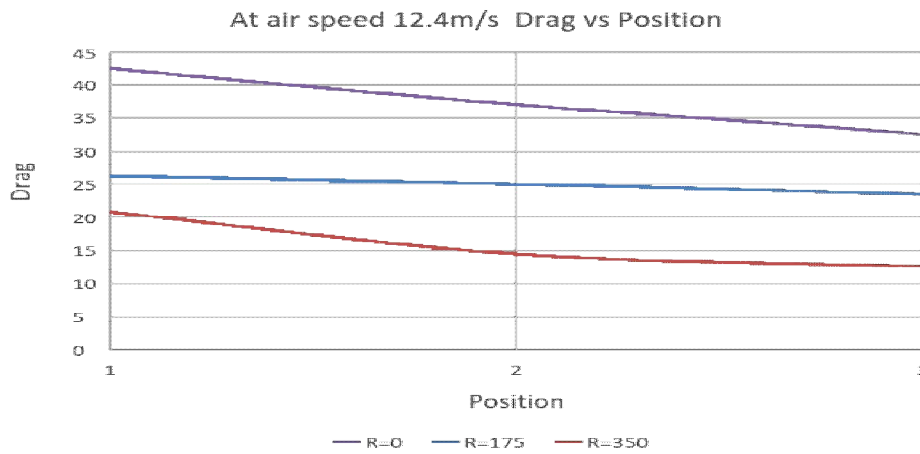
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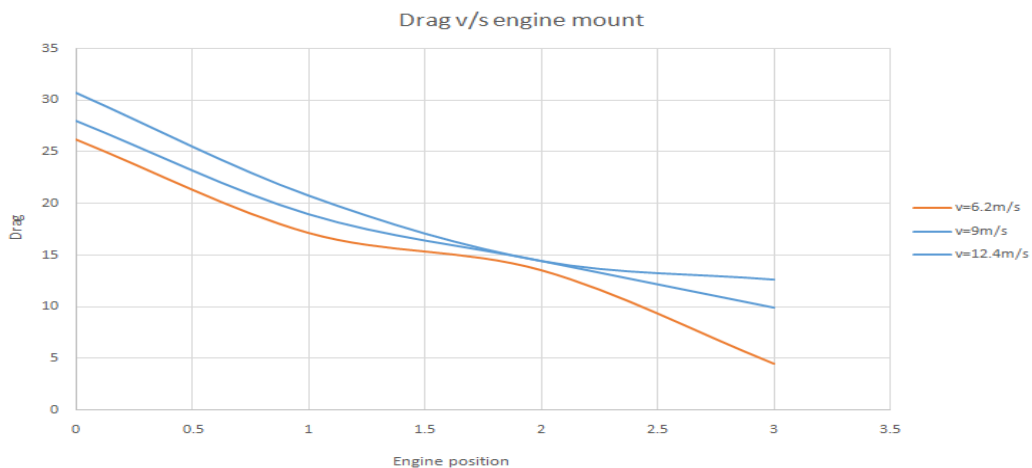
At air speed 12m/s Drag vs Position (Where Engine Motor RPM is throttle of wind tunnel)

Engine position	R=0	R=175	R=350
1	42.451	26.205	20.784
2	37.036	25.01	14.474
3	32.521	23.491	12.67



Graph – 3 (Drag vs Position at 12.4 m/s)

Engine position	Drag		
	v=6.2m/s	v=9m/s	v=12.4m/s
0	26.205	28.011	30.715
1	17.178	18.986	20.784
2	13.57	14.472	14.474
3	4.533	9.961	12.67



Graph – 4 (Drag vs Engine Mount)

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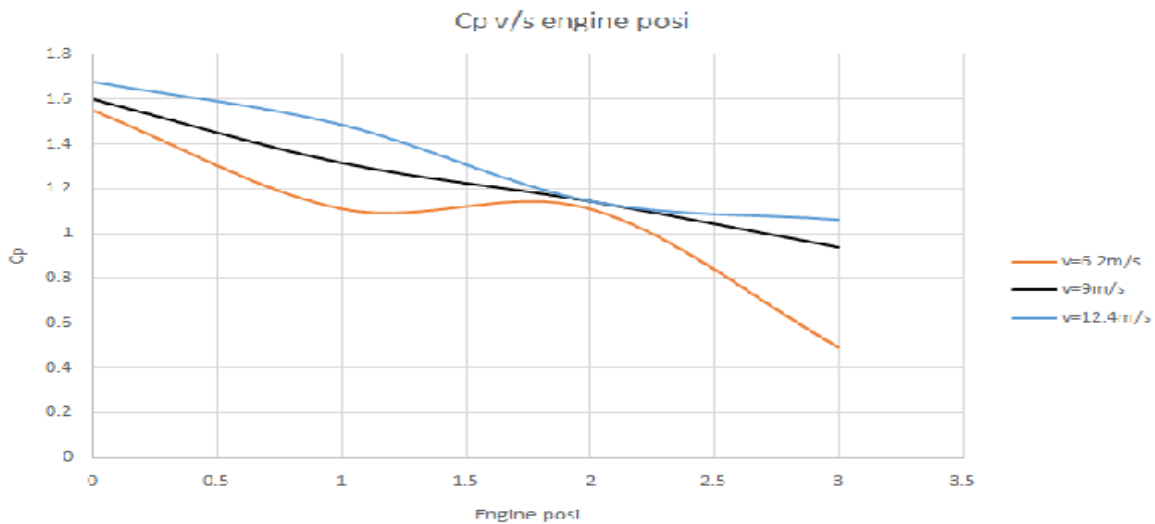
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Coefficient of Pressure

Engine position	v=6.2m/s	v=9m/s	v=12.4m/s
0	26.205	28.011	30.715
1	17.178	18.986	20.784
2	13.57	14.472	14.474
3	4.533	9.961	12.67



Graph – 5 (Cd vs Engine Position)

On the basis of position:

From the above data we concluded that as we move the engine towards the rear edge of the model, drag and coefficient of pressure are reduced gradually. Drag and coefficient of pressure are maximum for position 1 (i.e. 30cm from rear edge of model) which reduce when engine is moved to position 2(i.e. 20cm from rear edge of the model) and are minimum for position 3(i.e. 10cm from the rear edge of model).

Hence, position 3 (i.e. 10cm from the rear edge of the model) is most suitable to mount the engine.

On the basis of air speed:

From the above data we concluded that as we increase the air speed of wind tunnel, drag and coefficient of pressure are increasing gradually. Drag and coefficient of pressure are minimum for air speed 6.2m/s which increase when air speed is 9m/s and are maximum for air speed 12.4m/s.

Hence, air speed 6.2m/s is most suitable speed of wind tunnel.

On the basis of motor rpm:

From all the above observations we concluded that as we increase the motor rpm, drag and coefficient of pressure are reduced. Drag and coefficient of pressure are maximum for motor rpm 0, which reduce when motor rpm is 175 and are minimum for motor rpm 350.

Hence, we concluded that motor rpm 350 is most suitable.

From the above data we concluded that there is some drag over the model which is reduces due to introduction of tail engine.

Drag and coefficient of pressure is reduced by introducing tail engine.

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IV. CONCLUSIONS

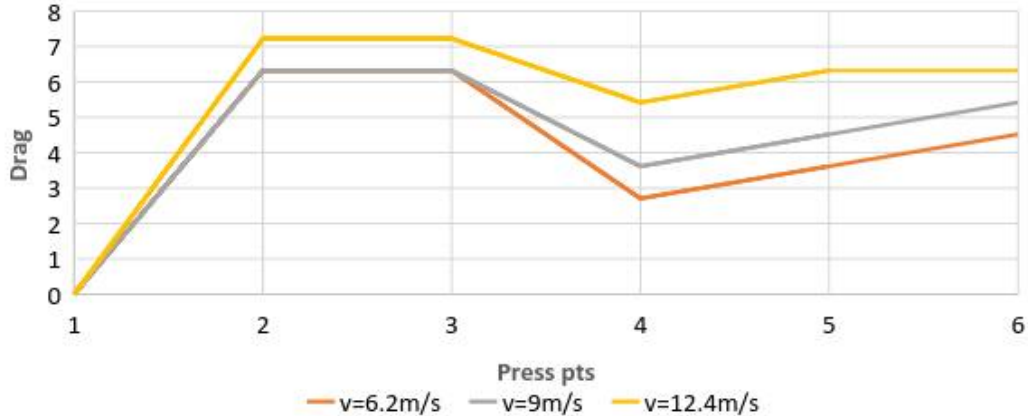
I. Without engine mounting, there will be more drag but after placing engine at the rear of the fuselage we concluded that the skin friction drag is reduced substantially.

Wind tunnel speed	Motor rpm	Position from rear of fuselage
6.2m/s	0	10cm
9m/s	175	20cm
12.4m/s	350	30cm

II. We tested our model at different conditions.

III. From above experimental result we concluded that, the drag is gradually decreasing as we are increasing rpm of mounted motor but when air flow velocity is increases, some drag also increases due to shift of air flow from laminar to the turbulence.

IV. At the rear of the fuselage we also observe that because of engine mounting drag is increased.



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