# International Journal of Innovative Research in Science, Engineering and Technology 

(A High I mpact Factor, Monthly, Peer Reviewed J ournal)

Visit: www.ijirset.com
Vol. 6, Issue 10, October 2017

# Roman and Strong Roman Domination Numbers in Graphs 

Narges Mohsenitonekaboni ${ }^{1}$, G. Suresh Singh ${ }^{2}$<br>Research Scholar, Department of Mathematics, University of Kerala, Kariavattom, Thiruvananthapuram, India ${ }^{1}$ Professor and Head, Department of Mathematics, University of Kerala, Kariavattom, Thiruvananthapuram, India ${ }^{2}$

ABSTRACT:Let $f: V \rightarrow\{0,1,2\}$ be a function having the property that for every vertex $v \in V$ with $f(v)=0$, there exists a neighbourhood $u \in N(v)$ with $f(u)=2$. Such a function is called a Roman dominating function or just an RDF. The weight of an RDF is the value $f(V)=\sum_{u \in V} f(u)$. The minimum weight of an RDF on $G$ is called the Roman domination number of $G$ and is denoted by $\gamma_{R}(G)$. The function $f: V \rightarrow\{0,1,2,3\}$ is named a Strong Roman dominating function on a graph $G$ whenever for each vertex $u$ with $f(u)=0$ there exists an adjacent vertex $v$ to $u$ such that $f(v)=3$. Also for each vertex $u$ with $f(u)=1$ there should be at least an adjacent vertex $v$ to $u$ weighted 2. The weight of an SRDF is the value $f(V)=\sum_{u \in V} f(u)$. Strong Roman domination number of graph $G$ which we denoted by $\gamma_{S R}(G)$ is minimum weight of an SRDF on $G$. In this paper, we show that

$$
\frac{1}{2} \gamma_{S R}(G) \leq \gamma_{R}(G) \leq \frac{2}{3} \gamma_{S R}(G)
$$

And we study the Roman and Strong Roman domination of the trees and we show that $\gamma_{R}(T)=\frac{2}{3} \gamma_{S R}(T)$.
KEYWORDS: Roman domination, Strong Roman domination, Tree.

## I. Introduction

For notations and graph theoretic terminologies not defined herein, we refer [3, 4, 9]. Let $G=(V, E)$ be a finite simple graph with the vertex set $V=V(G)$ and the edge set $E=E(G)$. Let $|V(G)|=n(G)=n$ be the order of graph $G$. For any vertex $v \in V$, the open neighbourhood of $v$ is the set $N(v)=\{u \in V \mid u v \in E\}$ and the closed neighbourhood of $v$ is the set $N[v]=N(v) \bigcup\{v\}$. For a set $S \subseteq V$, the open neighbourhood of $S$ is the set $N(S)=\bigcup_{v \in S} N(v)$ and the closed neighbourhood of $S$ is the set $N[S]=N(S) \cup S$. The degree of a vertex $v \in V$ is equals to $|N(v)|$ and denoted by $\operatorname{deg}(v)$. The maximum and minimum degree of a graph $G$ are

# International Journal of Innovative Research in Science, Engineering and Technology 

(A High Impact Factor, Monthly, Peer Reviewed J ournal)<br>Visit: www.ijirset.com<br>Vol. 6, Issue 10, October 2017

denoted by $\Delta(G)$ and $\delta(G)$, respectively. Let $S \subset V$ be any subset of vertices of $G$. Then the induced sub$\operatorname{graph} G[S]$ is the graph whose set is $S$ and whose edge set consists of all of the edges in $E$ that have both endpoints in $S$. The induced sub-graph $G[S]$ may also be called the sub-graph induced in $G$ by $S$. A walk in a graph $G$ is a finite sequence $W=v_{0} e_{1} v_{1} e_{2} v_{2} \ldots e_{n} v_{n}$ whose terms are alternatively vertices and edges such that for $1 \leq i \leq n$ the ends of $e_{i}$ are $v_{i-1}$ and $v_{i}$. The length of a walk is the number of edges occur in the walk. The distance between two vertices $u$ and $v$ in graph $G$ is the minimum length of a path joining them. The diameter of a graph $G$ is the maximum distance between vertices of $G$, denoted $\operatorname{diam}(G)$. The minimum diameter of graph $G$ is called a diagonal in $G$. A non-trivial graph, is a graph $G$ of order at least 2 . A walk consisting of $k+1$ distinct vertices $v_{0} v_{1} \ldots v_{k}$ is a path, and if $v_{0}=v_{k}$ then these vertices form a cycle. A graph $G$ is connected if for every pair of vertices $v$ and $x$ in $V(G)$, there is a $v-x$ path. Otherwise, $G$ is disconnected. A tree $T$ is a connected graph with no cycles. Every tree $T$ with $n$ vertices has $m=n-1$ edges. A Star $K_{1, n}$ is a tree with a vertex of degree $n$ and $n$ vertices of degree 1 . Observe that a star is a type of tree. A leaf is a vertex with degree 1 and a Support vertex is an adjacent vertex to a leaf. A Strong support vertex is a vertex which adjacent to at lest two leaves. In this paper, all support vertices and all leaves of tree $T$ are denoted by $S(T)$ and $L(T)$, respectively. A rooted tree $T$ distinguishes one vertex $r$ called the root. For each vertex $v \neq r$ of $T$ the parent of $v$ is the neighbourhood of $v$ on the unique $(r, v)$ - path, while a child of $v$ is any other neighbourhood of $v$. A simple graph $G$, is said to be complete if each pair of distinct vertices is joined by an edge. Generally $K_{n}$ denotes a complete graph on $n$ vertices. The complement $\bar{G}$ of a graph $G$ has $V(\bar{G})=V(G)$ and $\{u, v\} \in E(G)$ if and only if $\{u, v\} \notin E(\bar{G})$. Thus, the complement of a complete graph is the empty graph.

A set $S \subseteq V$ is a dominating setif $N[S]=V$. The domination number is the minimum cardinality of a dominating set in $G$ and denoted by $\gamma(G)$, see [2].

A Roman dominating function on a graph $G=(V, E)$ is a function $f: V \rightarrow\{0,1,2\}$ satisfying the condition that every vertex $u$ for which $f(u)=0$ is adjacent to at least one vertex $v$ for which $f(v)=2$. The weight of a Roman dominating function is the value $f(V)=\sum_{u \in V} f(u)$. The minimum weight of a Roman dominating function on a graph $G$ is called the Roman domination number of $G$ which is denoted by $\gamma_{R}(G)$, see [1, 10, 11].

Other notations and terminologies not explicitly given here could be find in [3, 4, 5, 6, 12]. K. Selvakumar et al. in [7] introduced Strong Roman domination in 2016. A Strong Roman dominating function on a graph $G=(V, E)$ is a function $f: V \rightarrow\{0,1,2,3\}$ satisfying the condition that every vertex $u$ for which $f(u)=0$ is adjacent to at least one vertex $v$ for which $f(v)=3$ and also every vertex $u$ for which $f(u)=1$ is adjacent to at least one vertex $v$ for which $f(v)=2$. The weight of a Strong Roman dominating function is the value $f(V)=\sum_{u \in V} f(u)$. The minimum weight of a Strong Roman dominating function on a graph $G$ is called

## International Journal of Innovative Research in Science, Engineering and Technology

(A High I mpact Factor, Monthly, Peer Reviewed Journal)<br>Visit: www.ijirset.com

Vol. 6, I ssue 10, October 2017
the Strong Roman domination number of $G$ which is denoted by $\gamma_{S R}(G)$. A Strong Roman dominating function can be displayed with $f=\left(V_{0}, V_{1}, V_{2}, V_{3}\right)$, or $f=\left(V_{0}^{f}, V_{1}{ }^{f}, V_{2}^{f}, V_{3}^{f}\right)$ to refer to $f$, where $V_{i}=\{v \in V(G) \mid f(v)=i\},(i=0,1,2,3)$. Clearly in a Strong Roman dominating function of weight $\gamma_{S R}(G)$, no vertex needs to be assigned the value 1 . Therefore, we can assume that for each Strong Roman domination function, $V_{1}=\phi$. In this paper, we show that

$$
\frac{1}{2} \gamma_{S R}(G) \leq \gamma_{R}(G) \leq \frac{2}{3} \gamma_{S R}(G)
$$

and characterize the Lower bound. Also, we characterize all trees $T$ with $\gamma_{R}(T)=\frac{2}{3} \gamma_{S R}(T)$.
In this paper we quote the following Theorems from [7, 8].
Theorem 1 [8]: For any graph $G$,

$$
2 \gamma(G) \leq \gamma_{S R}(G) \leq 3 \gamma(G)
$$

Theorem 2 [7]: For any graph $G$,

$$
\gamma_{R}(G) \leq \gamma_{S R}(G)
$$

Theorem 3 [7]: Let $f=\left(V_{0}, V_{1}, V_{2}, V_{3}\right)$ be any $\gamma_{S R}(G)$ - function. Then
a) $G\left[V_{2}\right]$ has maximum degree 0 .
b) No edge of $G$ joins $V_{2}$ and $V_{3}$.
c) No edge of $G$ joins $V_{1}$ and $V_{3}$.

## II. MAIN RESULTS

Firs, we present the Lower and Upper bound on Roman domination number on Strong Roman domination number.
Theorem 4: For any graph $G$,

$$
\frac{1}{2} \gamma_{S R}(G) \leq \gamma_{R}(G) \leq \frac{2}{3} \gamma_{S R}(G)
$$

Proof:Let $f=\left(V_{0}, \phi, V_{2}, V_{3}\right)$ be a $\gamma_{S R}(G)$-function. In this case, the function $f^{\prime}=\left(V_{0}^{\prime}, V_{1}^{\prime}, V_{2}^{\prime}\right)$, where $V_{0}^{\prime}=V_{0}, V_{1}^{\prime}=V_{2}$ and $V_{2}^{\prime}=V_{3}$ is an RDF on graph $G$. Therefore

$$
\begin{align*}
\gamma_{R}(G) & \leq f^{\prime}(V) \\
& =\left|V_{1}^{\prime}\right|+2\left|V_{2}^{\prime}\right| \\
& =\left|V_{2}\right|+2\left|V_{3}\right|  \tag{1}\\
& =2\left|V_{2}\right|+3\left|V_{3}\right|-\left(\left|V_{2}\right|+\left|V_{3}\right|\right) \\
& =\gamma_{S R}(G)-\left(\left|V_{2}\right|+\left|V_{3}\right|\right)
\end{align*}
$$

## International Journal of Innovative Research in Science, Engineering and Technology

(A High Impact Factor, Monthly, Peer Reviewed Journal)<br>Visit: www.ijirset.com

## Vol. 6, I ssue 10, October 2017

Since $V_{2} \cup V_{3}$ is dominating set on graph $G$, we have $\gamma(G) \leq\left|V_{2}\right|+\left|V_{3}\right|$ and thus from (1) we have

$$
\begin{align*}
\gamma_{R}(G) & \leq \gamma_{S R}(G)-\left(\left|V_{2}\right|+\left|V_{3}\right|\right)  \tag{2}\\
& \leq \gamma_{S R}(G)-\gamma(G)
\end{align*}
$$

Using Theorem 1, $\gamma_{S R}(G) \leq 3 \gamma(G)$ implies $\frac{1}{3} \gamma_{S R}(G) \leq \gamma(G)$. Therefore from (2) we have

$$
\begin{aligned}
\gamma_{R}(G) & \leq \gamma_{S R}(G)-\gamma(G) \\
& \leq \gamma_{S R}(G)-\frac{1}{3} \gamma(G) \\
& =\frac{2}{3} \gamma_{S R}(G)
\end{aligned}
$$

Hence the Upper bound exists.Now, to prove the existence of Lower bound, assume that $g=\left(V_{0}, V_{1}, V_{2}\right)$ is a $\gamma_{R}(G)$ - function. In this case, the function $g^{\prime}=\left(V_{0}^{\prime}, \phi, V_{2}^{\prime}, V_{3}^{\prime}\right)$, where $V_{0}^{\prime}=V_{0}, V_{2}^{\prime}=V_{1}$ and $V_{3}^{\prime}=V_{2}$ is an SRDF on graph $G$. Therefore

$$
\begin{aligned}
\gamma_{R}(G) & \leq g^{\prime}(V) \\
& =2\left|V_{2}^{\prime}\right|+3\left|V_{3}^{\prime}\right| \\
& =2\left|V_{1}\right|+3\left|V_{2}\right| \\
& \leq 2\left|V_{1}\right|+4\left|V_{2}\right| \\
& =2 \gamma_{S R}(G) .
\end{aligned}
$$

So, $\gamma_{S R}(G) \leq 2 \gamma_{R}(G)$ and thus $\frac{1}{2} \gamma_{S R}(G) \leq \gamma_{R}(G)$.
Hence the proof follows. $\square$
Note that, the Upper bound in Theorem 4 can be viewed as an extension of the Upper bound in Theorem 2 for all graphs. Also, the boundaries presented in Theorem 4 are sharp. For sharpness of Lower and Upper bound we consider the trivial graph $K_{1}$ and path $P_{5}$, respectively. In next theorem we characterize the boundaries with $\frac{1}{2} \gamma_{S R}(G)=\gamma_{R}(G)$.
Theorem 5: Let $G$ be a graph of order $n$. Then $\frac{1}{2} \gamma_{S R}(G)=\gamma_{R}(G)$ if and only if $G=\bar{K}_{n}$.
Proof:Suppose that $f=\left(V_{0}, V_{1}, V_{2}\right)$ is a $\gamma_{R}(G)$ - function, such that $V_{2}$ is maximum. In this case, the function $f^{\prime}=\left(V_{0}^{\prime}, \phi, V_{2}^{\prime}, V_{3}^{\prime}\right)$, where $V_{0}^{\prime}=V_{0}, V_{2}^{\prime}=V_{1}$ and $V_{3}^{\prime}=V_{2}$ is an SRDF on graph $G$. Therefore

## International Journal of Innovative Research in Science, Engineering and Technology

## (A High Impact Factor, Monthly, Peer Reviewed Journal)

Visit: www.ijirset.com
Vol. 6, Issue 10, October 2017

$$
\begin{aligned}
2 \gamma_{R}(G) & =\gamma_{S R}(G) \\
& \leq f^{\prime}(V) \\
& =2\left|V_{2}^{\prime}\right|+3\left|V_{3}^{\prime}\right| \\
& =2\left|V_{1}\right|+3\left|V_{2}\right| \\
& \leq 2\left|V_{1}\right|+4\left|V_{2}\right| \\
& =2 \gamma_{R}(G) .
\end{aligned}
$$

From this above relation it follows that

$$
2\left|V_{1}\right|+3\left|V_{2}\right|=2\left|V_{1}\right|+4\left|V_{2}\right|,
$$

therefore $\left|V_{2}\right|=0$. Since we chose $f$ such that $V_{2}$ is maximum, we have $V_{1}$ is an independent set and thus $G=\bar{K}_{n}$.

The converse part is obvious.

$$
\text { III. CHARACTERIZATION OF THE TREES WITH } \gamma_{R}(T)=\frac{2}{3} \gamma_{S R}(T)
$$

First, we begin with following supporting Lemmas.
Lemma 6: For any graph $G$,

$$
\gamma_{R}(G)=\frac{2}{3} \gamma_{S R}(G),
$$

if and only if $\gamma_{S R}(G)=3 \gamma(G)$ and $\gamma_{R}(G)=2 \gamma(G)$.
Proof:Suppose that $\gamma_{R}(G)=\frac{2}{3} \gamma_{S R}(G)$ and $f=\left(V_{0}, \phi, V_{2}, V_{3}\right)$ is a $\gamma_{S R}(G)-$ function. In this case, the function $g=\left(V_{0}^{\prime}, V_{1}^{\prime}, V_{2}^{\prime}\right)$, where $V_{0}^{\prime}=V_{0}, V_{1}^{\prime}=V_{2}$ and $V_{2}^{\prime}=V_{3}$ is an $\operatorname{SRDF}$ on graph $G$. Therefore

$$
\begin{aligned}
\frac{2}{3} \gamma_{S R}(G) & =\gamma_{R}(G) \\
& \leq g(V) \\
& =\left|V_{1}^{\prime}\right|+2\left|V_{2}^{\prime}\right| \\
& =\left|V_{2}\right|+2\left|V_{3}\right| \\
& \leq \gamma_{S R}(G)-\left|V_{2}\right|-\left|V_{3}\right| \\
& \leq \gamma_{S R}(G)-\gamma(G) .
\end{aligned}
$$

So, $\quad \frac{2}{3} \gamma_{S R}(G) \leq \gamma_{S R}(G)-\gamma(G)$ and thus $3 \gamma(G) \leq \gamma_{S R}(G)$.From Theorem 1 , we have $\gamma_{S R}(G) \leq 3 \gamma(G)$. Hence $\gamma_{S R}(G)=3 \gamma(G)$, also

## International Journal of Innovative Research in Science, Engineering and Technology

(A High Impact Factor, Monthly, Peer Reviewed J ournal)<br>Visit: www.ijirset.com

Vol. 6, Issue 10, October 2017

$$
\begin{aligned}
\gamma_{R}(G) & =\frac{2}{3} \gamma_{S R}(G) \\
& =\frac{2}{3}(3 \gamma(G)) \\
& =2 \gamma(G) .
\end{aligned}
$$

The converse part is obvious.
Lemma 7: Let for any graph $G$ with $\gamma_{R}(G)=\frac{2}{3} \gamma_{S R}(G)$, the function $f=\left(V_{0}, \phi, V_{2}, V_{3}\right)$ be a $\gamma_{S R}(G)-$ function. Then $V_{2}=\phi$.
Proof:Let $f^{\prime}=\left(V_{0}^{\prime}, V_{1}^{\prime}, V_{2}^{\prime}\right)$, where $V_{0}^{\prime}=V_{0}, V_{1}^{\prime}=V_{2}$ and $V_{2}^{\prime}=V_{3}$ be an RDF on graph $G$. Therefore

$$
\begin{aligned}
\frac{2}{3} \gamma_{S R}(G) & =\gamma_{R}(G) \\
& \leq f^{\prime}(V) \\
& =\left|V_{1}^{\prime}\right|+2\left|V_{2}^{\prime}\right| \\
& =\left|V_{2}\right|+2\left|V_{3}\right| \\
& \leq \gamma_{S R}(G)-\left|V_{2}\right|-\left|V_{3}\right| .
\end{aligned}
$$

Thus

$$
\begin{aligned}
\left|V_{2}\right|+2\left|V_{3}\right| & \leq \frac{1}{3} \gamma_{S R}(G) \\
& =\frac{2\left|V_{2}\right|+3\left|V_{3}\right|}{3} \\
& =\frac{2}{3}\left|V_{2}\right|+\left|V_{3}\right| .
\end{aligned}
$$

So, $\left|V_{2}\right| \leq \frac{2}{3}\left|V_{2}\right|$ and hence $\left|V_{2}\right|=0$. Then $V_{2}=\phi$.
Our aim is to characterize all trees with Upper bound where equality holds in Theorem 4. Let F be a family of trees $T$ which is obtained from a sequence of trees $T_{1}, T_{2}, \ldots, T_{j},(j \geq 1)$ such that $T_{1}$ is a Star $K_{1, r}$, $(r \geq 1)$ and if $j \geq 2$, then $T_{j}$ can be obtained from $T_{j-1}$ with one of the five Operations $\varphi_{1}, \varphi_{2}, \varphi_{3}, \varphi_{4}$ and $\varphi_{5}$ as shown in figures $1,2,3,4$ and 5 , respectively.
Operation $\varphi_{\mathbf{1}}$ : Let $u$ be a Strong support vertex of $T_{i}$. In this case, $T_{i+1}$ is obtained from $T_{i}$ by adding a new vertex $v$ and adding the edge $u v$. (see Figure 1)
Operation $\varphi_{\boldsymbol{\nu}}$ : Let $u \in V\left(T_{i}\right)$ and $\gamma_{R}\left(T_{i}-u\right) \geq \gamma_{R}\left(T_{i}\right)$. In this case, $T_{i+1}$ is obtained from $T_{i}$ by adding a Star $K_{1,2}$ with central vertex $v$ and adding the edge $u v$. (see Figure 2)

## International Journal of Innovative Research in Science, Engineering and Technology

(A High Impact Factor, Monthly, Peer Reviewed J ournal)<br>Visit: www.ijirset.com

Vol. 6, Issue 10, October 2017
Operation $\varphi_{\mathbf{2}}$ : Let $u \in V\left(T_{i}\right)$. In this case, $T_{i+1}$ is obtained from $T_{i}$ by adding a Star $K_{1,2}$ with central vertex $v$ and leaf $w$ and adding the edge $u w$. (see Figure 3)
Operation $\varphi_{\boldsymbol{\Delta}}$ : Let $u \in V\left(T_{i}\right)$. In this case, $T_{i+1}$ is obtained from $T_{i}$ by adding a Star $K_{1,3}$ with central vertex $v$ and leaf $w$ and adding the edge $u w$. (see Figure 4)
Operation $\varphi_{\mathbf{5}}$ : Let $u \in V\left(T_{i}\right)$ and $\gamma_{R}\left(T_{i}-u\right) \geq \gamma_{R}\left(T_{i}\right)$. In this case, $T_{i+1}$ is obtained from $T_{i}$ by adding a Path $P_{5}$ with central vertex $v$ and adding the edge $u v$. (see Figure 5)


Figure 1.Operation $\varphi_{1}$.



Figure 2.Operation $\varphi_{2}$.



Figure 5.Operation $\varphi_{5}$.

## International Journal of Innovative Research in Science, Engineering and Technology

(A High I mpact Factor, Monthly, Peer Reviewed Journal)<br>Visit: www.ijirset.com

## Vol. 6, Issue 10, October 2017

In the following, we show that each tree $T$ of family $F$ satisfy the condition $\gamma_{R}\left(T_{i}\right)=\frac{2}{3} \gamma_{S R}\left(T_{i}\right)$.
Lemma 8: If $\gamma_{R}\left(T_{i}\right)=\frac{2}{3} \gamma_{S R}\left(T_{i}\right)$ and $T_{i+1}$ is obtained from $T_{i}$ with Operation $\varphi_{1}$, then

$$
\gamma_{R}\left(T_{i+1}\right)=\frac{2}{3} \gamma_{S R}\left(T_{i+1}\right)
$$

Proof:Suppose that $f$ is a $\gamma_{S R}\left(T_{i}\right)$ - function. Then, since $u$ is a strong support vertex, we have $f(u)=3$.
We can extend the function $f$ to an SRDF on tree $T_{i+1}$ by assigning the weight 0 to the vertex $v$. Therefore

$$
\begin{aligned}
\gamma_{S R}\left(T_{i+1}\right) & \leq f(V) \\
& =\gamma_{S R}\left(T_{i}\right)
\end{aligned}
$$

Always $\gamma_{R}\left(T_{i}\right) \leq \gamma_{S R}\left(T_{i+1}\right)$. Hence $\gamma_{S R}\left(T_{i+1}\right)=\gamma_{S R}\left(T_{i}\right)$. Assume the same way, $g$ is a $\gamma_{R}\left(T_{i}\right)$ - function. Since $u$ is a strong support vertex, we get $f(u)=2$ and thus we can extend the function $g$ to an RDF on tree $T_{i+1}$ by assigning the weight 0 to the vertex $v$. Therefore

$$
\begin{aligned}
\gamma_{S R}\left(T_{i+1}\right) & \leq g(V) \\
& =\gamma_{R}\left(T_{i}\right)
\end{aligned}
$$

Since always $\gamma_{R}\left(T_{i}\right) \leq \gamma_{S R}\left(T_{i+1}\right)$, we have $\gamma_{S R}\left(T_{i}\right)=\gamma_{S R}\left(T_{i+1}\right)$.
So,

$$
\begin{aligned}
\gamma_{R}\left(T_{i+1}\right) & =\gamma_{R}\left(T_{i}\right) \\
& =\frac{2}{3} \gamma_{S R}\left(T_{i}\right) \\
& =\frac{2}{3} \gamma_{S R}\left(T_{i+1}\right)
\end{aligned}
$$

Hence $\gamma_{R}\left(T_{i+1}\right)=\frac{2}{3} \gamma_{S R}\left(T_{i+1}\right)$. $\square$
Lemma 9: If $\gamma_{R}\left(T_{i}\right)=\frac{2}{3} \gamma_{S R}\left(T_{i+1}\right)$ and $T_{i+1}$ is obtained from $T_{i}$ with Operation $\varphi_{2}$, then

$$
\gamma_{R}\left(T_{i+1}\right)=\frac{2}{3} \gamma_{S R}\left(T_{i+1}\right)
$$

Proof:Suppose that $u \in V\left(T_{i}\right)$ and $\gamma_{R}\left(T_{i}-u\right) \geq \gamma_{R}\left(T_{i}\right)$. Let $v$ be a vertex of Star $K_{1,2}$ relative to Operation $\varphi_{2}$. If $D$ is a dominating set for tree $T_{i}$, then $D \bigcup\{v\}$ is a dominating set for tree $T_{i+1}$. Therefore

$$
\begin{equation*}
\gamma\left(T_{i+1}\right)<\gamma\left(T_{i}\right)+1 \tag{1}
\end{equation*}
$$

Now, suppose that $f$ is a $\gamma_{S R}\left(T_{i+1}\right)$ - function. Since $\left.f\right|_{T_{i}}$ is an SRDF on tree $T_{i}$, we have

## International Journal of Innovative Research in Science, Engineering and Technology

(A High I mpact Factor, Monthly, Peer Reviewed Journal)<br>Visit: www.ijirset.com

Vol. 6, I ssue 10, October 2017

$$
\begin{aligned}
\gamma_{S R}\left(T_{i}\right) & \leq g\left(\left.V\right|_{T_{i}}\right) \\
& =f(V)-3 \\
& =\gamma_{S R}\left(T_{i+1}\right)-3
\end{aligned}
$$

Otherwise, $\left.f\right|_{T_{i}-u}$ is an SRDF on tree $T_{i}-u$. Thus

$$
\begin{aligned}
\gamma_{S R}\left(T_{i}\right) & =\frac{3}{2} \gamma_{R}\left(T_{i}\right) \\
& \leq \frac{3}{2} \gamma_{R}\left(T_{i}-u\right) \\
& \leq \gamma_{S R}\left(T_{i}-u\right) \\
& \leq f\left(\left.V\right|_{T_{i}-u}\right) \\
& \leq f(V)-3 \\
& =\gamma_{S R}\left(T_{i+1}\right)-3
\end{aligned}
$$

Therefore, in this case, $\gamma_{S R}\left(T_{i}\right) \leq \gamma_{S R}\left(T_{i+1}\right)-3$.
Any $\gamma_{S R}\left(T_{i}\right)$ - function can be extended to an SRDF on tree $T_{i+1}$ by assigning the weight 3 to the vertex $v$ and the weight 0 to all its neighbouring vertices. Therefore $\gamma_{S R}\left(T_{i+1}\right) \leq \gamma_{S R}\left(T_{i}\right)+3$ which implies that $\gamma_{S R}\left(T_{i+1}\right)=\gamma_{S R}\left(T_{i}\right)+3$. Now, from (1) and Lemma 6 we have

$$
\begin{aligned}
\gamma_{S R}\left(T_{i+1}\right) & =\gamma_{S R}\left(T_{i}\right)+3 \\
& =3 \gamma\left(T_{i}\right)+3 \\
& =3 \gamma\left(T_{i+1}\right) .
\end{aligned}
$$

Any $\gamma_{R}\left(T_{i}\right)$ - function can be extended to an RDF on tree $T_{i+1}$ by assigning the weight 2 to the vertex $v$ and 0 to all its neighbouring vertices. Therefore $\gamma_{R}\left(T_{i+1}\right) \leq \gamma_{R}\left(T_{i}\right)+2$.Also, if $g$ is a $\gamma_{R}\left(T_{i+1}\right)-$ function, then since $v$ is a Strong support vertex, we have $g(v)=2$. If $f(u) \neq 0$, then $\left.g\right|_{T_{i}}$ is an RDF on tree $T_{i}$. Thus

$$
\begin{aligned}
\gamma_{R}\left(T_{i}\right) & \leq g\left(\left.V\right|_{T_{i}}\right) \\
& =g(V)-2 \\
& =\gamma_{R}\left(T_{i+1}\right)-2
\end{aligned}
$$

And in case $g(u)=0$, then $\left.g\right|_{T_{i}-u}$ is an RDF on tree $T_{i}-u$. Therefore

## International Journal of Innovative Research in Science, Engineering and Technology

(A High Impact Factor, Monthly, Peer Reviewed J ournal)<br>Visit: www.ijirset.com

Vol. 6, I ssue 10, October 2017

$$
\begin{aligned}
\gamma_{R}\left(T_{i}\right) & \leq \gamma_{R}\left(T_{i}-u\right) \\
& \leq g\left(\left.V\right|_{T_{i}-u}\right) \\
& =g(V)-2 \\
& =\gamma_{R}\left(T_{i+1}\right)-2 .
\end{aligned}
$$

Thus in each case, $\gamma_{R}\left(T_{i}\right) \leq \gamma_{R}\left(T_{i+1}\right)-2$ and since we showed that $\gamma_{R}\left(T_{i+1}\right) \leq \gamma_{R}\left(T_{i}\right)+2$.So,

$$
\gamma_{R}\left(T_{i+1}\right)=\gamma_{R}\left(T_{i}\right)+2
$$

Now, from (1) and Lemma 6 we have

$$
\begin{aligned}
\gamma_{R}\left(T_{i+1}\right) & =\gamma_{R}\left(T_{i}\right)+3 \\
& =2 \gamma\left(T_{i}\right)+2 \\
& =2 \gamma\left(T_{i+1}\right) .
\end{aligned}
$$

Hence $\quad \gamma_{S R}\left(T_{i+1}\right)=3 \gamma\left(T_{i+1}\right)$ and $\quad \gamma_{R}\left(T_{i+1}\right)=2 \gamma\left(T_{i+1}\right)$. Thus Lemma 6 implying that $\gamma_{R}\left(T_{i+1}\right)=\frac{2}{3} \gamma\left(T_{i+1}\right)$.
Lemma 10: If $\gamma_{R}\left(T_{i}\right)=\frac{2}{3} \gamma\left(T_{i}\right)$ and $T_{i+1}$ is obtained from $T_{i}$ with Operation $\varphi_{3}$, then

$$
\gamma_{R}\left(T_{i+1}\right)=\frac{2}{3} \gamma\left(T_{i+1}\right)
$$

Proof: Suppose that $u \in V\left(T_{i}\right)$ and $v$ is the central vertex and $w$ and $x$ are the leaves of Star $K_{1,2}$, respectively. If $D$ is a $\gamma\left(T_{i}\right)-$ set , then $D \bigcup\{v\}$ is a dominating set on tree $T_{i+1}$. Therefore
$\gamma\left(T_{i+1}\right) \leq \gamma\left(T_{i}\right)+1$.
Suppose that $f$ is a $\gamma_{S R}\left(T_{i+1}\right)$ - function. Clearly, we can assume that $f(v)=3$ and $f(x)=f(w)=0$. Therefore $\left.f\right|_{T_{i}}$ is an SRDF on tree $T_{i}$ and thus

$$
\begin{aligned}
\gamma_{S R}\left(T_{i}\right) & \leq f\left(\left.V\right|_{T_{i}}\right) \\
& =f(V)-3 \\
& =\gamma_{S R}\left(T_{i+1}\right)-3 .
\end{aligned}
$$

Any $\gamma_{S R}\left(T_{i}\right)$ - function can be extended to an SRDF on tree $T_{i+1}$ by assigning the weight 3 to the vertex $v$ and the weight 0 to all its neighbouring vertices. Therefore

$$
\gamma_{S R}\left(T_{i+1}\right) \leq \gamma_{S R}\left(T_{i}\right)+3
$$

And thus based on previous

$$
\begin{aligned}
\gamma_{S R}\left(T_{i+1}\right) & =\gamma_{S R}\left(T_{i}\right)+3 \\
& =\gamma_{S R}\left(T_{i+1}\right)
\end{aligned}
$$

## International Journal of Innovative Research in Science, Engineering and Technology

(A High Impact Factor, Monthly, Peer Reviewed J ournal)<br>Visit: www.ijirset.com

Vol. 6, I ssue 10, October 2017
Now, from (1) and Lemma 6 we have

$$
\begin{aligned}
\gamma_{S R}\left(T_{i+1}\right) & =3 \gamma\left(T_{i+1}\right) \\
& \leq 3 \gamma\left(T_{i}\right)+3 \\
& \leq \gamma_{S R}\left(T_{i}\right)+3 \\
& =\gamma_{S R}\left(T_{i+1}\right) .
\end{aligned}
$$

Therefore $\gamma_{S R}\left(T_{i+1}\right)=3 \gamma\left(T_{i+1}\right)$.Now, to prove the problem based on Lemma 6 , we have its enough to show that $\gamma_{R}\left(T_{i+1}\right)=2 \gamma\left(T_{i+1}\right)$. Let $g$ be a $\gamma_{R}\left(T_{i+1}\right)$-function. In this case, we can assume that $g(v)=2$ and $g(x)=g(w)=0$. Therefore $\left.g\right|_{T_{i}}$ is an RDF on tree $T_{i}$. And thus

$$
\begin{aligned}
\gamma_{R}\left(T_{i}\right) & \leq g\left(\left.V\right|_{T_{i}}\right) \\
& =g(V)-2 \\
& =\gamma_{R}\left(T_{i+1}\right)-2
\end{aligned}
$$

Any $\gamma_{R}\left(T_{i}\right)$ - function can be extended to an RDF on tree $T_{i+1}$ by assigning the weight 2 to the vertex $v$ and the weight 0 to all its neighbouring vertices. Therefore $\gamma_{R}\left(T_{i+1}\right) \leq \gamma_{R}\left(T_{i}\right)+2$.
Hence $\gamma_{R}\left(T_{i+1}\right)=\gamma_{R}\left(T_{i}\right)+2$. Now, from (1) and Lemma 6 we have

$$
\begin{aligned}
\gamma_{R}\left(T_{i+1}\right) & \leq 2 \gamma\left(T_{i+1}\right) \\
& \leq 2 \gamma\left(T_{i}\right)+2 \\
& =\gamma_{R}\left(T_{i}\right)+2 \\
& =\gamma_{R}\left(T_{i+1}\right)
\end{aligned}
$$

So,

$$
\gamma_{R}\left(T_{i+1}\right)=2 \gamma\left(T_{i+1}\right)
$$

Hence the proof. $\square$
Lemma 11: If $\gamma_{R}\left(T_{i}\right)=\frac{2}{3} \gamma_{S R}\left(T_{i}\right)$ and $T_{i+1}$ is obtained from $T_{i}$ with Operation $\varphi_{4}$, then

$$
\gamma_{R}\left(T_{i+1}\right)=\frac{2}{3} \gamma_{S R}\left(T_{i+1}\right)
$$

Proof:Suppose that $u$ is a vertex of tree $T_{i}$ and $w$ is a leaf of Star $K_{1,2}$ with central vertex $v$ relative to Operation $\varphi_{4}$. If $D$ is a dominating set on tree $T_{i}$, then $D \bigcup\{v\}$ is a dominating set on tree $T_{i+1}$. Therefore

$$
\begin{equation*}
\gamma\left(T_{i+1}\right) \leq \gamma\left(T_{i}\right)+1 \tag{1}
\end{equation*}
$$

Any $\gamma_{S R}\left(T_{i}\right)$ - function can be extended to an SRDF on tree $T_{i+1}$ by assigning the weight 3 to the vertex $v$ and the weight 0 to all its neighbouring vertices. Therefore

$$
\gamma_{S R}\left(T_{i+1}\right) \leq \gamma_{S R}\left(T_{i}\right)+3
$$

## International Journal of Innovative Research in Science, Engineering and Technology

(A High Impact Factor, Monthly, Peer Reviewed J ournal)<br>Visit: www.ijirset.com

Vol. 6, I ssue 10, October 2017
Suppose that $f$ is a $\gamma_{S R}\left(T_{i+1}\right)$ - function. Since $v$ is a Strong support vertex, we have $f(v)=3$. Also, we can assume that $f(w)=0$. In this case, $\left.f\right|_{T_{i}}$ is an SRDF on tree $T_{i}$. Thus

$$
\begin{aligned}
\gamma_{S R}\left(T_{i}\right) & \leq f\left(\left.V\right|_{T_{i}}\right) \\
& =f(V)-3 \\
& =\gamma_{S R}\left(T_{i+1}\right)-3
\end{aligned}
$$

Therefore $\gamma_{S R}\left(T_{i+1}\right)=\gamma_{S R}\left(T_{i}\right)+3$. Now, from (1) and Lemma 6 we have

$$
\begin{aligned}
\gamma_{S R}\left(T_{i+1}\right) & =3 \gamma\left(T_{i+1}\right) \\
& \leq 3 \gamma\left(T_{i}\right)+3 \\
& \leq \gamma_{S R}\left(T_{i}\right)+3 \\
& =\gamma_{S R}\left(T_{i+1}\right) .
\end{aligned}
$$

Hence $\gamma_{S R}\left(T_{i+1}\right)=3 \gamma\left(T_{i+1}\right)$. Now, suppose that $f$ is a $\gamma_{R}\left(T_{i+1}\right)-$ function. Since $v$ is a Strong support vertex, we can suppose that $f(v)=3$ and each of its neighbouring vertices has the weight 0 . Therefore $\left.f\right|_{T_{i}}$ is an RDF on tree $T_{i}$. Thus $\gamma_{R}\left(T_{i}\right) \leq \gamma_{R}\left(T_{i+1}\right)-2$. Any $\gamma_{R}\left(T_{i}\right)$-function can be extended to an RDF by assigning the weight 2 to the vertex $v$ and the weight 0 to all its neighbouring vertices. Therefore $\gamma_{R}\left(T_{i+1}\right) \leq \gamma_{R}\left(T_{i}\right)+2$. So,

$$
\gamma_{R}\left(T_{i+1}\right)=\gamma_{R}\left(T_{i}\right)+2
$$

Hence based on Lemma 6 we have $\gamma_{R}\left(T_{i+1}\right)=\frac{2}{3} \gamma_{S R}\left(T_{i+1}\right)$. $\square$
Lemma 12: If $\gamma_{R}\left(T_{i}\right)=\frac{2}{3} \gamma_{S R}\left(T_{i}\right)$ and $T_{i+1}$ is obtained from $T_{i}$ with Operation $\varphi_{5}$, then

$$
\gamma_{R}\left(T_{i+1}\right)=\frac{2}{3} \gamma_{S R}\left(T_{i+1}\right)
$$

Proof: Let $u \in V\left(T_{i}\right)$ and $P_{5}=x y v w z$ be a Path with five vertices relative to Operation $\varphi_{5}$. If $D$ is a $\gamma\left(T_{i}\right)-$ set , then $D \bigcup\{y, w\}$ is a dominating set on tree $T_{i+1}$. Therefore

$$
\begin{equation*}
\gamma\left(T_{i+1}\right) \leq \gamma\left(T_{i}\right)+2 \tag{1}
\end{equation*}
$$

Assume that $f$ is a $\gamma_{R}\left(T_{i+1}\right)$ - function. If $f(v) \neq 2$, then $\left.f\right|_{T_{i}}$ is an RDF on tree $T_{i}$.
Since $f\left(V\left(P_{5}\right)\right) \geq 4$, we have

$$
\begin{aligned}
\gamma_{R}\left(T_{i}\right) & \leq f\left(\left.V\right|_{T_{i}}\right) \\
& =f(V)-4 \\
& =\gamma_{R}\left(T_{i+1}\right)-4
\end{aligned}
$$

## International Journal of Innovative Research in Science, Engineering and Technology

(A High Impact Factor, Monthly, Peer Reviewed J ournal)<br>Visit: www.ijirset.com

Vol. 6, I ssue 10, October 2017
Now, suppose that $f(v)=2$. In this case, we can assume that $f(u)=0$ and therefore $\left.f\right|_{T_{i}-u}$ is an RDF on tree $T_{i}-u$. Based on assumption we have

$$
\begin{aligned}
\gamma_{R}\left(T_{i}\right) & \leq \gamma_{R}\left(T_{i}-u\right) \\
& \leq f\left(\left.V\right|_{T_{i}-u}\right) \\
& =f(V)-4 \\
& =\gamma_{R}\left(T_{i+1}\right)-4 .
\end{aligned}
$$

Thus in each case, $\gamma_{R}\left(T_{i}\right) \leq \gamma_{R}\left(T_{i+1}\right)-4$. Any $\gamma_{R}\left(T_{i}\right)-$ function can be extended to an RDF on tree $T_{i+1}$ by assigning the weight 2 to $y$ and $w$ and the weight 0 to $x, v$ and $z$. Therefore $\gamma_{R}\left(T_{i+1}\right) \leq \gamma_{R}\left(T_{i}\right)+4$. Then same as before $\gamma_{R}\left(T_{i+1}\right)=\gamma_{R}\left(T_{i}\right)+4$.Now, from (1) and Lemma 6 we have

$$
\begin{aligned}
\gamma_{R}\left(T_{i+1}\right) & \leq 2 \gamma\left(T_{i+1}\right) \\
& \leq 2 \gamma\left(T_{i}\right)+4 \\
& =\gamma_{R}\left(T_{i}\right)+4 \\
& =\gamma_{R}\left(T_{i+1}\right) .
\end{aligned}
$$

So, we conclude that $\gamma_{R}\left(T_{i+1}\right)=2 \gamma\left(T_{i+1}\right)$. Based on Lemma 6, it is enough to show that $\gamma_{S R}\left(T_{i+1}\right)=3 \gamma\left(T_{i+1}\right)$. If $g$ is a $\gamma_{S R}\left(T_{i}\right)-$ function, then the function $g$ can be extended to an SRDF on tree $T_{i+1}$ by assigning the weight 3 to $y$ and $w$ and the weight 0 to $x, v$ and $z$. Therefore $\gamma_{S R}\left(T_{i+1}\right) \leq \gamma_{S R}\left(T_{i}\right)+6$.Now, suppose that $f$ is a $\gamma_{S R}\left(T_{i+1}\right)-$ function. If $f(u) \neq 0$, then $\left.f\right|_{T_{i}}$ is an SRDF on tree $T_{i}$ and also $f\left(V\left(P_{5}\right)\right) \geq 6$. Therefore

$$
\begin{aligned}
\gamma_{S R}\left(T_{i}\right) & \leq g\left(\left.V\right|_{T_{i}}\right) \\
& =g(V)-6 \\
& =\gamma_{S R}\left(T_{i+1}\right)-6 .
\end{aligned}
$$

Otherwise, $g(u)=0$. Then $\left.g\right|_{T_{i}-u}$ is an SRDF on tree $T_{i}-u$. Based on assumption $\gamma_{R}\left(T_{i-u}\right) \geq \gamma_{R}\left(T_{i}\right)$. So,

## International Journal of Innovative Research in Science, Engineering and Technology

(A High Impact Factor, Monthly, Peer Reviewed J ournal)<br>Visit: www.ijirset.com

Vol. 6, I ssue 10, October 2017

$$
\begin{aligned}
\gamma_{S R}\left(T_{i}\right) & =\frac{3}{2} \gamma_{R}\left(T_{i}\right) \\
& \leq \frac{3}{2} \gamma_{R}\left(T_{i}-u\right) \\
& \leq \gamma_{S R}\left(T_{i}-u\right) \\
& \leq g\left(\left.V\right|_{T_{i}-u}\right) \\
& \leq g(V)-6 \\
& =\gamma_{S R}\left(T_{i+1}\right)-6 .
\end{aligned}
$$

Therefore in each case, $\gamma_{S R}\left(T_{i}\right) \leq \gamma_{S R}\left(T_{i+1}\right)-6$ and since we showed that earlier $\gamma_{S R}\left(T_{i+1}\right) \leq \gamma_{S R}\left(T_{i}\right)+6$. Hence $\gamma_{S R}\left(T_{i+1}\right)=\gamma_{S R}\left(T_{i}\right)+6$.Now, from (1), Lemma 6 and Theorem 1 we have

$$
\begin{aligned}
\gamma_{S R}\left(T_{i+1}\right) & \leq 3 \gamma\left(T_{i+1}\right) \\
& \leq 3 \gamma\left(T_{i}\right)+6 \\
& \leq \gamma_{S R}\left(T_{i}\right)+6 \\
& =\gamma_{S R}\left(T_{i+1}\right)
\end{aligned}
$$

Therefore $\gamma_{S R}\left(T_{i+1}\right)=3 \gamma\left(T_{i+1}\right)$ and thus the problem is solved.
In this section we provide a constructive characterization of trees with $\gamma_{R}(T)=\frac{2}{3} \gamma_{S R}(T)$.
Theorem 13: The tree $T$ satisfies the condition $\gamma_{R}(T)=\frac{2}{3} \gamma_{S R}(T)$ if and only if $T \in \mathcal{F}$.
Proof: First we use induction on the order $n \geq 3$ of the tree $T$ in which $\gamma_{R}(T)=\frac{2}{3} \gamma_{S R}(T)$.If $\operatorname{diam}(T)=2$, then $T$ is a Star. Therefore $T \in$ F.Now, assume that $\operatorname{diam}(T)=3$. Thus $T$ is a Double Star $\left(S_{r, s}\right)$ on $1 \leq s \leq r$. Let $s=1$. In this case, $T$ includes a vertex $v$ of degree 2 which has exactly an adjacent leaf. The function in which the adjacent leaves to $v$ have the weight 3 and all the other vertices have the weight 0 is a $\gamma_{S R}(T)-$ function. Therefore $\gamma_{S R}(T)=5$. Also, the function in which the adjacent leaves to $v$ have the weight 2 , the non-adjacent leaves to $v$ have the weight 3 and all the other vertices have the weight 0 is a $\gamma_{R}(T)-$ function. Therefore $\gamma_{R}(T)=3$. Hence $\gamma_{R}(T) \neq \frac{2}{3} \gamma_{S R}(T)$ which is a contradiction. Thus $S \geq 2$. Let $u$ be a non-adjacent leaf to $v$. Then $T$ is a Double Star with central vertices $u$ and $v$ where $\operatorname{deg}(u) \geq 3$ and $\operatorname{deg}(v) \geq 3$. We consider $T_{1}$ and $T_{2}$ are two components of $T-a b$ where $u \in V\left(T_{1}\right)$ and $v \in V\left(T_{2}\right)$. Clearly, $T_{i},(i=1,2)$ is a Star of order at least 3 . Therefore $\gamma_{R}\left(T_{i}\right)=2$ and $\gamma_{S R}\left(T_{i}\right)=3,(i=1,2)$.If $\operatorname{deg}(v)=3$, since $\gamma_{R}\left(T_{1}-u\right) \geq \gamma_{R}\left(T_{1}\right)$, then the tree $T$ is obtained from $T_{1} \in \mathrm{~F}$ by Operation $\varphi_{2}$.Now, assume that $\operatorname{deg}(v) \geq 4$

# International Journal of Innovative Research in Science, Engineering and Technology 

(A High Impact Factor, Monthly, Peer Reviewed J ournal)<br>Visit: www.ijirset.com

## Vol. 6, I ssue 10, October 2017

and $w$ is adjacent leaf to $v$. We put $T^{\prime}=T-w$. In this case, it is obvious that $\gamma_{R}\left(T^{\prime}\right)=4$ and $\gamma_{S R}\left(T^{\prime}\right)=6$. So, $\gamma_{R}\left(T^{\prime}\right)=\frac{2}{3} \gamma_{S R}\left(T^{\prime}\right)$. Therefore under the hypothesis, $T^{\prime} \in \mathrm{F}$. Thus $T$ is obtained from $T^{\prime}$ by Operation $\varphi_{1}$. Hence we can assume that $\operatorname{diam}(T) \geq 4$. Let $T$ has support vertex $u$ with at least three adjacent leaves and $w$ be adjacent leaf to $u$. We put $T^{\prime}=T-w$. We show that $T^{\prime} \in$ F. It is enough to prove that $\gamma_{R}\left(T^{\prime}\right)=2 \gamma\left(T^{\prime}\right)$ and $\gamma_{S R}\left(T^{\prime}\right)=3 \gamma\left(T^{\prime}\right)$.Assume that $D$ is a $\gamma\left(T^{\prime}\right)-$ set on tree $T^{\prime}$. Since $u$ is a support vertex on tree $T^{\prime}$, we get $u \in D$. Since in the tree $T$ and the vertex $u$ is adjacent to $w$, we get $D$ is a dominating set on tree $T$. Thus $\gamma(T) \leq|D|=\gamma\left(T^{\prime}\right)$. Always $\gamma\left(T^{\prime}\right) \leq \gamma(T)$. Therefore $\gamma(T)=\gamma\left(T^{\prime}\right)$.
Let $f$ be a $\gamma_{R}\left(T^{\prime}\right)$-function. Since $u$ is a Strong support vertex, we get $f(u)=2$ and thus $f$ can be extended to an RDF on tree $T$ by assigning the weight 0 to the vertex $w$. Therefore, based on Theorem 1 and Lemma 6 we have

$$
\begin{aligned}
\gamma_{R}(T) & \leq f(V) \\
& =\gamma_{R}\left(T^{\prime}\right) \\
& \leq 2 \gamma\left(T^{\prime}\right) \\
& =2 \gamma(T) \\
& =2 \gamma_{R}(T) .
\end{aligned}
$$

Hence $\gamma_{R}(T)=2 \gamma(T)$.Now, assume that $g$ is a $\gamma_{S R}\left(T^{\prime}\right)-$ function. Since $u$ is a Strong support vertex, we get $g(u)=3$. Thus $g$ can be extended to an SRDF on tree $T$ by assigning the weight 0 to the vertex $w$. Therefore, from Theorem 1 and Lemma 6 we have

$$
\begin{aligned}
\gamma_{S R}(T) & \leq g(V) \\
& =\gamma_{S R}\left(T^{\prime}\right) \\
& \leq 3 \gamma\left(T^{\prime}\right) \\
& =3 \gamma(T) \\
& =\gamma_{S R}(T) .
\end{aligned}
$$

Then $\gamma_{S R}\left(T^{\prime}\right)=3 \gamma\left(T^{\prime}\right)$. So, $T^{\prime} \in \mathrm{F}$ and thus $T$ is obtained from $T^{\prime}$ by Operation $\varphi_{1}$. Hence $T \in \mathrm{~F}$. We say assume for the next, the following holds.

$$
\text { Fact: } T \text { has no Strong support vertex with three adjacent leaves to it. }
$$

Let $x_{0} x_{1} \ldots x_{d}$ be a Diagonal path. We root the tree $T$ at vertex $x_{0}$. Based on Fact, $\operatorname{deg}\left(x_{d-1}\right) \leq 3$. We consider the following cases:

Case 1: $\operatorname{deg}\left(x_{d-1}\right)=3$. Let $\operatorname{deg}\left(x_{d-1}\right) \geq 3$. In this case, each child of $x_{d-2}$ is a support vertex with a leaf.
We put $T^{\prime}=T-T_{x_{d-1}}$. If $D$ is a $\gamma(T)-$ set, since $x_{d-2}$ is either a support vertex or has a support vertex adjacent to it. Therefore, $D-\left\{x_{d-1}\right\}$ is a dominating set on tree $T^{\prime}$. Thus

## International Journal of Innovative Research in Science, Engineering and Technology

(A High Impact Factor, Monthly, Peer Reviewed J ournal)<br>Visit: www.ijirset.com

Vol. 6, I ssue 10, October 2017

$$
\begin{aligned}
\gamma\left(T^{\prime}\right) & \leq|D|-1 \\
& =\gamma(T)-1 .
\end{aligned}
$$

Any $\gamma\left(T^{\prime}\right)$-set can be extended to a dominating set on tree $T$ by adding $x_{d-1}$ to it. Therefore $\gamma(T) \leq \gamma\left(T^{\prime}\right)+1$.Hence $\gamma(T)=\gamma\left(T^{\prime}\right)+1$.Let $f$ be a $\gamma_{S R}\left(T^{\prime}\right)-$ function. In this case, the function $f$ can be extended to an SRDF on tree $T$ by assigning the weight 3 to $x_{d-1}$ and the weight 0 to all their neighbouring leaves. Therefore $\gamma_{S R}(T) \leq \gamma_{S R}\left(T^{\prime}\right)+3$. Now, from Lemma 6 and Theorem 1 we have

$$
\begin{aligned}
\gamma_{S R}(T) & \leq \gamma_{S R}\left(T^{\prime}\right)+3 \\
& \leq 3 \gamma\left(T^{\prime}\right)+3 \\
& =3 \gamma(T) \\
& =\gamma_{S R}(T)
\end{aligned}
$$

Therefore $\gamma_{S R}\left(T^{\prime}\right)=3 \gamma\left(T^{\prime}\right)$. Also, if $g$ is a $\gamma_{R}\left(T^{\prime}\right)-$ function, then $g$ can be extended to an RDF on tree $T$ by assigning the weight 2 to $x_{d-1}$ and the weight 0 to all their neighbouring leaves. Therefore $\gamma_{R}(T) \leq \gamma_{R}\left(T^{\prime}\right)+2$.Now, from Theorem 1 and Lemma 6 we have

$$
\begin{aligned}
\gamma_{R}(T) & \leq \gamma_{R}\left(T^{\prime}\right)+2 \\
& \leq 2 \gamma\left(T^{\prime}\right)+2 \\
& =2 \gamma(T) \\
& =\gamma_{R}(T) .
\end{aligned}
$$

It follows from above relation that $\gamma_{R}\left(T^{\prime}\right)=2 \gamma\left(T^{\prime}\right)$.Also, we showed that before $\gamma_{S R}\left(T^{\prime}\right)=3 \gamma\left(T^{\prime}\right)$. Therefore it follows from Lemma 6 that $\gamma_{R}\left(T^{\prime}\right)=\frac{2}{3} \gamma_{S R}\left(T^{\prime}\right)$.So, by the induction hypothesis $T^{\prime} \in \mathrm{F}$. Now, suppose that $\gamma_{R}\left(T^{\prime}-x_{d-2}\right)<\gamma_{R}\left(T^{\prime}\right)$. In this case, if $f^{\prime}$ is a $\gamma_{R}\left(T^{\prime}-x_{d-2}\right)-$ function, then the function $f^{\prime}$ can be extended to an RDF on tree $T$ by assigning the weight 2 to $x_{d-1}$ and the weight 0 to all their neighbouring. Therefore $\gamma_{R}(T) \leq \gamma_{R}\left(T^{\prime}-x_{d-2}\right)+2$.So,

$$
\begin{aligned}
\gamma_{R}(T) & \leq \gamma_{R}\left(T^{\prime}-x_{d-2}\right)+2 \\
& \leq \gamma_{R}\left(T^{\prime}\right)+2 \\
& =2 \gamma\left(T^{\prime}\right)+2 \\
& =2 \gamma(T) \\
& =\gamma_{R}(T),
\end{aligned}
$$

Which is a contradiction.Thus $\gamma_{R}\left(T^{\prime}-x_{d-2}\right) \geq \gamma_{R}\left(T^{\prime}\right)$ and therefore $T$ is obtained from $T^{\prime}$ by Operation $\varphi_{2}$. Hence $T \in$ F.Now, suppose that $\operatorname{deg}\left(x_{d-2}\right)=2$. We put $T^{\prime}=T-T_{x_{d-2}}$. Let $D$ be a $\gamma(T)-$ set .

# International Journal of Innovative Research in Science, Engineering and Technology 

(A High Impact Factor, Monthly, Peer Reviewed Journal)<br>Visit: www.ijirset.com

## Vol. 6, I ssue 10, October 2017

Clearly, we can assume $x_{d-2} \notin D$ and $x_{d-1} \in D$. In this case, $D-\left\{x_{d-1}\right\}$ is a dominating set on tree $T^{\prime}$. Therefore $\gamma\left(T^{\prime}\right) \leq \gamma(T)-1$. Any $\gamma\left(T^{\prime}\right)-$ set can be extended to a dominating set on tree $T$ by adding $x_{d-1}$ to it. Thus $\gamma(T) \leq \gamma\left(T^{\prime}\right)+1$ and therefore $\gamma(T)=\gamma\left(T^{\prime}\right)+1$. Now, let $g^{\prime}$ be a $\gamma_{R}\left(T^{\prime}\right)$ - function. In this case, the function $g^{\prime}$ can be extended to an RDF on tree $T$ by assigning the weight 2 to $x_{d-1}$ and the weight 0 to all its neighbouring. Therefore $\gamma_{R}(T) \leq \gamma_{R}\left(T^{\prime}\right)+2$. From Lemma 6 Theorem 1 we have

$$
\begin{aligned}
\gamma_{R}(T) & \leq \gamma_{R}\left(T^{\prime}\right)+2 \\
& \leq 2 \gamma\left(T^{\prime}\right)+2 \\
& =2 \gamma(T) \\
& =\gamma_{R}(T) .
\end{aligned}
$$

It is implied from above relation that $\gamma_{R}\left(T^{\prime}\right)=2 \gamma_{R}\left(T^{\prime}\right)$. Also, if $f^{\prime}$ is a $\gamma_{S R}\left(T^{\prime}\right)-$ function, then the function $f^{\prime}$ can be extended to an SRDF on tree $T$ by assigning the weight 3 to $x_{d-1}$ and the weight 0 to all its neighbouring. Therefore $\gamma_{S R}(T) \leq \gamma_{S R}\left(T^{\prime}\right)+3$.From Lemma 6 and Theorem 1 we have

$$
\begin{aligned}
\gamma_{S R}(T) & \leq \gamma_{S R}\left(T^{\prime}\right)+2 \\
& \leq 3 \gamma\left(T^{\prime}\right)+3 \\
& =3 \gamma(T) \\
& =\gamma_{S R}(T)
\end{aligned}
$$

Above relation implies that $\gamma_{S R}\left(T^{\prime}\right)=3 \gamma\left(T^{\prime}\right)$. Considering the Lemma 6 and what we already showed $\gamma_{R}\left(T^{\prime}\right)=2 \gamma\left(T^{\prime}\right)$, we conclude $\gamma_{R}\left(T^{\prime}\right)=\frac{2}{3} \gamma_{S R}\left(T^{\prime}\right)$. So, with the inductive hypothesis we have $T^{\prime} \in \mathrm{F}$. Thus $T$ is obtained from $T^{\prime}$ by Operation $\varphi_{4}$. Hence $T \in \mathrm{~F}$.
Case 2: $\operatorname{deg}\left(x_{d-2}\right)=2$.If $\operatorname{deg}\left(x_{d-2}\right) \geq 3$, then each child of $x_{d-2}$ is either a leaf or a support vertex of degree 2 . Since each support child of $x_{d-2}$ other than $x_{d-1}$ plays the same role of $x_{d-1}$, we can assume that have degree 2 . Let $f=\left(V_{0}, V_{1}, V_{2}, V_{3}\right)$, where $V_{1}=\phi$ be a $\gamma_{S R}(T)$-function. Since $\gamma_{R}(T)=\frac{2}{3} \gamma_{S R}(T)$, based on Lemma 7, we get $V_{2}=\phi$.Therefore if $f\left(x_{d-2}\right) \neq 0$, then $f\left(x_{d-2}\right)=3$ holds. In this case, we can assume that $f\left(x_{d-1}\right)=0$ and $f\left(x_{d-2}\right)=2$ which is a contradiction with $V_{2}=\phi$.Therefore $f\left(x_{d-2}\right)=0$. In this case, $x_{d-2}$ does not have adjacent leaf. Otherwise, the adjacent leaf should be weighted 2 which is a contradiction with $V_{2}=\phi$. We show that in this case $x_{d-2}$ has at most an adjacent support other than $x_{d-1}$. On contrary suppose that $u_{1}$ and $u_{2}$ are two support children of $x_{d-2}$ other

## International Journal of Innovative Research in Science, Engineering and Technology

(A High Impact Factor, Monthly, Peer Reviewed J ournal)<br>Visit: www.ijirset.com

## Vol. 6, I ssue 10, October 2017

than $x_{d-1}$. Let $v_{1}$ and $v_{2}$ be adjacent leaves to $u_{1}$ and $u_{2}$, respectively. Since $V_{2}=\phi$, we can assume $f\left(u_{1}\right)=f\left(u_{2}\right)=3$ and $f\left(v_{1}\right)=f\left(v_{2}\right)=v$. In this case, we define the function $g$ as follows: Let us

$$
\begin{aligned}
& g\left(x_{d}\right)=g\left(v_{1}\right)=g\left(v_{2}\right)=2 \\
& g\left(x_{d-1}\right)=g\left(u_{1}\right)=g\left(u_{2}\right)=0 \\
& g\left(x_{d-2}\right)=3
\end{aligned}
$$

and other vertices take the same weight of the function. In this case, $g$ is a $\gamma_{S R}(T)-$ function, where the set of vertices have weight 2 are non-empty is contradiction with Lemma 7. Therefore $x_{d-2}$ has at most a support child other than $x_{d-1}$. Let $u$ be a support child of $x_{d-2}$ other than $x_{d-1}$ and $v$ be an adjacent leaf to $x_{d-2}$. We put $T^{\prime}=T-T_{x_{d-2}}$. If $D^{\prime}$ is a $\gamma\left(T^{\prime}\right)-$ set, then $D^{\prime} \bigcup\left\{x_{d-1}, u\right\}$ is a dominating set on tree $T$. Therefore $\gamma(T) \leq \gamma\left(T^{\prime}\right)+2$. On the other hand, if $\left\{x_{d-1}, u\right\} \subseteq D$ and $x_{d-2} \notin D$, then $D-\left\{x_{d-1}, u\right\}$ is a dominating set on tree $T^{\prime}$. Thus $\gamma\left(T^{\prime}\right) \leq \gamma(T)-2$. Consequently, we conclude that $\gamma(T)=\gamma\left(T^{\prime}\right)+2$.Now, let $f^{\prime}$ be a $\gamma_{S R}\left(T^{\prime}\right)$-function, then the function $f^{\prime}$ can be extended to an SRDF on tree $T$ by assigning the weight 3 to $x_{d-1}$ and $u$ and the weight 0 to all their neighbouring. Therefore $\gamma_{S R}(T) \leq \gamma_{S R}\left(T^{\prime}\right)+6$. Now, from Lemma 6 and Theorem 1, we conclude

$$
\begin{aligned}
\gamma_{S R}(T) & \leq \gamma_{S R}\left(T^{\prime}\right)+6 \\
& \leq 3 \gamma\left(T^{\prime}\right)+6 \\
& =3 \gamma(T) \\
& =\gamma_{S R}(T)
\end{aligned}
$$

Above relation implies that $\gamma_{S R}\left(T^{\prime}\right)=3 \gamma\left(T^{\prime}\right)$. Also, any $\gamma_{R}\left(T^{\prime}\right)-$ function can be extended to an RDF on tree $T$ by assigning the weight 2 to $x_{d-1}$ and $u$ and the weight 0 to all their neighbouring. Therefore $\gamma_{R}(T) \leq \gamma_{R}\left(T^{\prime}\right)+4$.From Lemma 6 and Theorem 1, we have

$$
\begin{aligned}
\gamma_{R}(T) & \leq \gamma_{S R}\left(T^{\prime}\right)+4 \\
& \leq 2 \gamma\left(T^{\prime}\right)+4 \\
& =2 \gamma(T) \\
& =\gamma_{R}(T)
\end{aligned}
$$

Therefore $\gamma_{R}\left(T^{\prime}\right)=2 \gamma_{R}\left(T^{\prime}\right)$. And so consider that $\gamma_{S R}\left(T^{\prime}\right)=3 \gamma\left(T^{\prime}\right)$, from Lemma 6 it implies that $\gamma_{R}\left(T^{\prime}\right)=\frac{2}{3} \gamma_{S R}\left(T^{\prime}\right)$. Hence assuming the induction $T^{\prime} \in$ F.Now, suppose that $\gamma_{R}\left(T^{\prime}-x_{d-3}\right)<\gamma_{R}\left(T^{\prime}\right)$. In this case, any $\gamma_{R}\left(T^{\prime}-x_{d-3}\right)-$ function can be extended to an RDF on tree $T$ by assigning the weight 2

# International Journal of Innovative Research in Science, Engineering and Technology 

(A High Impact Factor, Monthly, Peer Reviewed J ournal)<br>Visit: www.ijirset.com<br>\section*{Vol. 6, I ssue 10, October 2017}

to $x_{d-2}$, the weight 0 to $u$ and $x_{d-1}$ and the weight 1 to $v$ and $x_{d}$. Thus $\gamma_{R}(T) \leq \gamma_{R}\left(T^{\prime}-x_{d-3}\right)+4$. And therefore

$$
\begin{aligned}
\gamma_{R}(T) & \leq \gamma_{R}\left(T^{\prime}-x_{d-3}\right)+4 \\
& \leq \gamma_{R}\left(T^{\prime}\right)+4 \\
& \leq 2 \gamma\left(T^{\prime}\right)+4 \\
& =2 \gamma(T) \\
& =\gamma_{R}(T)
\end{aligned}
$$

which is a contradiction.So, $\gamma_{R}\left(T^{\prime}-x_{d-3}\right) \geq \gamma_{R}\left(T^{\prime}\right)$ and thus $T$ is obtained from $T^{\prime}$ with Operation $\varphi_{5}$.Hence $T \in$ F.Now, suppose that $\operatorname{deg}\left(x_{d-2}\right)=2$. We put $T^{\prime}=T-T_{x_{d-2}}$. If $D$ is a $\gamma(T)-s e t$, then we can assume that $x_{d-1} \in D$ and $x_{d-2} \notin D$. Therefore $D-\left\{x_{d-1}\right\}$ is a dominating set on tree $T^{\prime}$. Thus $\gamma\left(T^{\prime}\right) \leq \gamma(T)-1$. Since $\gamma\left(T^{\prime}\right)-$ set can be extended to a dominating set on tree $T$ by adding $x_{d-1}$ to it, we have $\gamma(T) \leq \gamma\left(T^{\prime}\right)+1$ and thus $\gamma(T)=\gamma\left(T^{\prime}\right)+1$.Now, suppose that $f$ is a $\gamma_{S R}(T)-$ function . Based on Lemma 7 there is no vertex which has weight 2 . Therefore we can assume that $f\left(x_{d}\right)=f\left(x_{d-2}\right)=0$ and $f\left(x_{d-1}\right)=3$. In this case, $\left.f\right|_{T^{\prime}}$ is a $\gamma_{S R}\left(T^{\prime}\right)-f$ function. Thus $\gamma_{S R}\left(T^{\prime}\right) \leq \gamma_{S R}(T)+3$. Any $\gamma_{S R}\left(T^{\prime}\right)-$ function can be extended to an SRDF on tree $T$ by assigning the weight 3 to $x_{d-1}$ and the weight 0 to all its neighbouring. Therefore, $\gamma_{S R}(T) \leq \gamma_{S R}\left(T^{\prime}\right)+3$.Consequently, we conclude that $\gamma_{S R}(T)=\gamma_{S R}\left(T^{\prime}\right)+3$ and in this case, based on Lemma 6, Theorem 1 and previous relation we have

$$
\begin{aligned}
\gamma_{S R}\left(T^{\prime}\right) & \leq \gamma_{S R}(T)-3 \\
& \leq 3 \gamma(T)-3 \\
& =3(\gamma(T)-1) \\
& =3 \gamma\left(T^{\prime}\right)
\end{aligned}
$$

Now, let $f$ be a $\gamma_{R}(T)$ - function. If $f\left(x_{d-2}\right)=2$ and $f\left(x_{d-3}\right)=0$, then $f\left(x_{d-1}\right)=0$ and $f\left(x_{d}\right)=1$. By changing the weight of $x_{d-2}$ and $x_{d}$ to 0 , the weight of $x_{d-1}$ to 2 and the weight of $x_{d-3}$ to 1 a new $\gamma_{R}(T)$-function is obtained such that $f\left(x_{d-2}\right)=0$.Also, if $f\left(x_{d-2}\right)=1$, then $f\left(x_{d}\right)+f\left(x_{d-1}\right)=2$. By changing the weight of $x_{d-2}$ and $x_{d}$ to 0 and the weight of $x_{d-1}$ to 2 an RDF with weight less than $\gamma_{R}(T)$ is obtained which is a contradiction.Therefore we can assume that $f\left(x_{d}\right)+f\left(x_{d-2}\right)=0$ and $f\left(x_{d-1}\right)=2$. Thus $\left.f\right|_{T^{\prime}}$ is an RDF on tree $T^{\prime}$. Hence $\gamma_{R}\left(T^{\prime}\right) \leq \gamma_{R}(T)-2$.Any $\gamma_{R}\left(T^{\prime}\right)$ - function can be extended to an RDF on tree $T$ by assigning the weight 2 to $x_{d-1}$ and the weight 0 to $x_{d}$ and $x_{d-2}$. Thus $\gamma_{R}(T) \leq \gamma_{R}\left(T^{\prime}\right)+2$. It follows from above

## International Journal of Innovative Research in Science, Engineering and Technology

(A High Impact Factor, Monthly, Peer Reviewed J ournal)<br>Visit: www.ijirset.com

Vol. 6, I ssue 10, October 2017
inequality that $\gamma_{R}(T)=\gamma_{R}\left(T^{\prime}\right)+2$.From Lemma 6 , Theorem 1 and $\gamma_{R}(T)=\gamma_{R}\left(T^{\prime}\right)+1$ we conclude that

$$
\begin{aligned}
\gamma_{R}\left(T^{\prime}\right) & \leq \gamma_{R}(T)-2 \\
& =2 \gamma(T)-2 \\
& =2 \gamma\left(T^{\prime}\right) .
\end{aligned}
$$

We have already show that $\gamma_{S R}\left(T^{\prime}\right)=3 \gamma\left(T^{\prime}\right)$ and the previous relation conclude that $T^{\prime} \in \mathrm{F}$ and $T$ is obtained from $T^{\prime}$ with Operation $\varphi_{3}$. Therefore $T \in \mathrm{~F}$.
Hence in each case $T \in \mathrm{~F}$.
Conversely, let $T \in \mathcal{F}$. In this case, by induction on the number of Operations that constructed the tree $T$ and by using Lemma $8,9,10,11$ and 12 we can show that $\gamma_{R}(T)=\frac{2}{3} \gamma_{S R}(T)$.

## REFERENCES

[1] Cockayne, E. J., Dreyer, P. A., Hedetniemi, S. M., and Hedetniemi, S. T. (2004). Roman domination in graphs. Discrete Mathematics, 278(1):1122.
[2] Dreyer, P. A. (2000). Applications and variations of domination in graphs. The State University of New Jersey, New Brunswick, NJ.
[3] Haynes, T. W., Hedetniemi, S. T., and Slater, P. J. (1998). Fundamentals of domination in graphs, volume 208 of monographs and textbooks in pure and applied mathematics.
[4] Haynes, T. W., Hedetniemi, S. T., and Slater, P. J. (1998). Domination in graphs: advanced topics, volume 209 of monographs and textbooks in pure and applied mathematics.
[5] Henning, M. A. (2003). Defending the roman empire from multiple attacks. Discrete Mathematics, 271(1):101-115.
[6] Pavlic, P. and Zerovnik, J. (2012). Roman domination number of the cartesian products of paths and cycles. The electronic journal of combinatorics, 19(3):P19.
[7] Selvakumar, K. and Kamaraj, M. (2016). Strong roman domination in graphs. International Journal of Mathematical Archive (IJMA) ISSN 22295046, 7(3).
[8] Singh, G. S., and Mohsenitonekaboni, N. (submitted). Some properties on Strong Roman domination in graphs.
[9] Singh, G. S. (2010). Graph Theory. PHI Learning Private Limited, New Delhi.
[10] Stewart, I. (1999). Defend the Roman Empire! Scientic American, 281:136-138.
[11] Sumenjak, T. K., Pavlic, P., and Tepeh, A. (2012). On the roman domination in the lexicographic product of graphs. Discrete Applied Mathematics, 160(13):2030-2036.
[12] Xueliang, F., Yuansheng, Y., and Baoqi, J. (2009). Roman domination in regular graphs. Discrete Mathematics, 309(6):1528-1537.

