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Influence of Temperature Dependent Properties and Gravity on Porous Thermoelastic Solid Due to Laser Pulse Heating With G-N Theory

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ABSTRACT: The present article deals with the gravity field and the laser pulse on porous thermoelastic solid under the effect of the temperature dependent properties in the context of the Green-Naghdi theory. The normal mode method used to obtain the exact solution of the considered physical quantities which have been shown graphically in the presence and the absence of the physical operators used in the problem.

KEYWORDS: Gravity, Green-Naghdi, Laser pulse, Normal mode, Porous, Temperature dependence, Thermoelasticity.

I.

INTRODUCTION

In the classical thermoelasticity (C-D) theory due to Biot [1], the equation of the heat conduction is a parabolic type. It could predict the infinite speed of the heat propagation in elastic media, but it was inconsistent with experimental observation. With this motivation, Lord and Shulman [2], and Green and Lindsay [3], established the (L-S) and (G-L) generalized thermoelasticity theories respectively. In the (L-S) theory, a relaxation time parameter introduced into the Fourier heat conduction equation, with the heat flux and its time derivative taken into account. The heat equation associated with this theory is essentially of a hyperbolic type. In the (G-L) theory, the constitutive equations were modified by introducing two relaxation time parameters. Both the equations of motion and heat conduction are of the hyperbolic type. The two theories can better characterize thermal disturbances with limited speed of the wave propagation and exhibit the so-called second sound effect in solids. Later, Green and Naghdi [4-6] established a new generalized thermoelasticity theory (G-N) theory of three types based on the energy and entropy balances, in which the energy dissipation was not considered in the previous theories. The linearized form of type I was equivalent to the classical thermoelasticity (C-D) theory. Type II describes the thermoelastic system without energy dissipation, while type III permits the dissipation of the energy. Therefore, the (G-N) theory is an ideal thermoelasticity theory. Ailawalia et al. [7] studied the effect of initial stress and rotation in (G-N) theory of type III. Othman et al. [8, 9] investigated the effect of rotation, the gravity and temperature dependent properties of porous thermoelastic solid with (G-N) theory. There are a number of theories about the mechanical properties of the porous materials. The concept of a distributed body introduced by Goodman and Cowin [10] in the context of granular and porous materials asserts that the mass density has the decomposition $\gamma^* \phi$ where γ^* is the density of the matrix material and ϕ is the volume fraction filed. This representation introduces an additional degree of kinematic freedom. Nunziato and Cowin [11] used this concept to present a non-linear theory to describe the properties of homogeneous elastic materials with voids free of fluid. Moreover, the theory of Cowin and Nunziato a more appropriated theory than other theories for the study of special continuum and geological materials, such as rocks, soils, and manufactured porous materials like ceramics and pressed powders. Generally, this theory based on the balance of energy, where the presence of the pores or voids involves an additional degree of freedom, called the fraction of elementary volume. In [12] Cowin and Nunziato established a theory to describe the linear elastic materials with voids. Iesan [13, 14] has developed a linear theory of



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thermoelastic materials with voids. The temperature dependence is an important physical property of materials reflecting the elastic deformation capacity of the material when subjected to an applied external load. Most of the investigations were done under the assumption of the temperature-independent material properties, which limit the applicability of the obtained solutions to certain ranges of temperature. At high temperature, the material characteristics such as the modulus of elasticity, Poisson's ratio, the coefficient of thermal expansion and the thermal conductivity are no longer constants [15]. In recent years due to the progress in various fields in science and technology the necessity of taking into consideration the real behaviour of the material characteristics prosperities as the temperature dependent measurements. In the classical theory of elasticity, the effect of the gravity neglected in a general manner. Bromwich [16] in particular on an elastic globe, was the first study the effect of the gravity of the problem of propagation of waves in solids. Laser at a high intensity when interacts with the solid surface, the absorption takes place. This in turn causes an internal energy gain of the substrate material and heat release from the irradiated region. Since the process, in general, is fast, the temperature gradients remain high in the irradiated region. This results in high thermal strain and thermally induced stresses in this region. The ultra-short lasers are those with the pulse duration ranging from nanoseconds to femto-seconds. In the case of ultra-short-pulsed laser heating, the high intensity, energy flux and ultrashort duration laser beam have introduced situations where very large thermal gradients or an ultra-high heating rate may exist on the boundaries by Sun et al. [17]. The microscopic two-step models, that is, parabolic and hyperbolic are useful for modifying the material as thin films. When a laser pulse heats a metal film, a thermoelastic wave generated due to thermal expansion near the surface. Othman et al. [18] investigated a model of thermoelasticity under thermal loading due to laser pulse.

This investigation studies the effect of the temperature dependent properties and the gravity field of porous thermoelastic solid heated by laser pulse with both types II and III of the (G-N) theory. The physical quantities obtained analytically. The physical quantities represented graphically in the presence and the absence of the gravity, the temperature dependent, the laser pulse and the porous effect.

II. BASIC EQUATIONS, FORMULATION AND SOLUTION OF THE PROBLEM

Following Green and Naghdi [5] of type III, Cowin and Nunziato [12], the field equations and the constitutive relations for a porous linear homogenous, isotropic thermoelastic solid without body forces, heat sources and extrinsic equilibrated body force and heated by a laser pulse, can be written as

$\sigma_{ij,j} = \rho u_i,$	(1)
$\begin{split} &\alpha \phi_{,ii} - b u_{k,k} - \xi_1 \phi - \omega_0 \phi_{,t} + mT = \rho \psi \phi_{,tt} , \\ &kT_{,ii} + k^* T_{,iit} - mT_0 \dot{\phi} = \rho C_e T_{,tt} + \beta T_0 e_{,tt} - \rho Q_{,t} , \\ &\sigma_{ij} = \lambda u_{k,k} \delta_{ij} + \mu (u_{i,j} + u_{j,i}) + b \phi \delta_{ij} - \beta T \delta_{ij} , i, j, k = 1, 2, 3, \end{split}$	(2)
	(3) (4)

Where, λ, μ are the Lame constants, $\alpha, b, \xi_1, \omega_0, m$ and ψ are the constants due to porous material, *T* is the absolute temperature, $\beta = (3\lambda + 2\mu)\alpha_t$ since α_t is the coefficient of thermal expansion, ρ is the density, C_e is the specific heat, *k* is the thermal conductivity, k^* is the material constant characteristic of the theory, T_0 is the reference temperature chosen so that $|(T - T_0)/T_0| << 1$, ϕ is the change in the volume fraction field, *e* is the dilation, e_{ij} is the strain components, σ_{ij} are the stress components, δ_{ij} is the Kronecker delta, and *Q* is the heat input of the laser pulse. When $k^* \rightarrow 0$ then (3) reduces to the heat conduction equation in (G-N) theory of type II. Consider a homogeneous, linear, porous and isotropic thermoelastic solid with half space $(y \ge 0)$, the rectangular Cartesian coordinate system (x, y, z) having originated on the surface z = 0. In equations for this problem a dot denotes differentiation with respect to time, while a comma denotes the material derivative. For two dimensional problem assume the dynamic displacement vector as u = (u, v, 0), all the considered quantities will be functions of the time variable and of the coordinates *x* the axis *y*. The laser pulse given by the heat input illuminates the plate surface



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$$Q = \frac{I_0 \gamma t}{2\pi r^2 t_0^2} \exp(-\frac{x^2}{r^2} - \frac{t}{t_0}) \exp(-\gamma y).$$

(6)

Where, I_0 is the energy absorbed, t_0 is the pulse rise time, r is the beam radius, x is the heat deposition due to the laser pulse is assumed to decay exponentially within the solid. To study the effect of the temperature dependence of modulus of elasticity, keeping the other elastic and thermal parameters, assuming that

 $\lambda=\lambda_{1}f\left(T\right), \quad \mu=\mu_{1}f\left(T\right), \quad \beta=\beta_{1}f\left(T\right), \quad \alpha=\alpha_{1}f\left(T\right), \quad \omega_{0}=\omega_{11}f\left(T\right), \quad \xi_{1}=\xi_{11}f\left(T\right), \quad \psi=\psi_{1}f\left(T\right), \quad m=m_{1}f\left(T\right), \quad b=b_{1}f\left(T\right).$

Where, $\lambda_1, \mu_1, \beta_1, \alpha_1, \omega_{11}, \xi_{11}, \psi_1, m_1, b_1$ are constants, $f(T) = (1 - \alpha^* T_0)$ is a non-dimensional function of temperature and α^* is the empirical material constant.

Equations (1)-(3) in the 2-D space under the effect of the gravity field under the temperature dependent investigation will be on the form

$$\nabla^2 u + (\lambda_1 + \mu_1/\mu_1) \frac{\partial e}{\partial x} + (b_1/\mu_1) \frac{\partial \phi}{\partial x} - (\beta_1/\mu_1) \frac{\partial T}{\partial x} + (\rho g/\mu_1 f(T)) \frac{\partial v}{\partial x} = (\rho/\mu_1 f(T)) \frac{\partial^2 u}{\partial t^2}, \tag{7}$$

$$\nabla^2 v + (\lambda_1 + \mu_1/\mu_1) \frac{\partial e}{\partial y} + (b_1/\mu_1) \frac{\partial \phi}{\partial y} - (\beta_1/\mu_1) \frac{\partial T}{\partial y} - (\rho g/\mu_1 f(T)) \frac{\partial u}{\partial x} = (\rho/\mu_1 f(T)) \frac{\partial^2 v}{\partial t^2},$$
(8)

$$\nabla^2 \phi - (b_1/\alpha_1) e - (\xi_{11}/\alpha_1) \phi - (\omega_{11}/\alpha_1) \frac{\partial \phi}{\partial t} + (m_1/\alpha_1) T = (\rho \psi_1/\alpha_1) \frac{\partial^2 \phi}{\partial t^2}, \tag{9}$$

$$k \nabla^{2}T + k^{*} \frac{\partial}{\partial t} \nabla^{2}T - m_{1}f(T)T_{0} \frac{\partial \phi}{\partial t} = \rho C_{e} \frac{\partial^{2}T}{\partial t^{2}} + \beta_{1}f(T) T_{0} \frac{\partial^{2}e}{\partial t^{2}} - \rho \frac{\partial}{\partial t}Q.$$
(10)

The equation can put in a more convenient form by using the following non-dimensional variables

$$(x', y', u', v') = \frac{\omega_{1}^{*}}{c_{1}}(x, y, u, v), \quad (\sigma_{ij}', p_{1}') = \frac{1}{\mu_{1}}(\sigma_{ij}, p_{1}), \quad \theta' = \frac{T}{T_{0}}, \quad g' = \frac{g}{c_{1}\omega_{1}^{*}}, \quad \phi' = \frac{\omega_{1}^{*2}\psi}{c_{1}^{2}}\phi, \quad t' = \omega_{1}^{*}t, \quad Q' = \frac{Q}{\omega_{1}^{*}T_{0}C_{e}}, \quad c_{1}^{2} = (\frac{\lambda_{1} + 2\mu_{1}}{\rho}) \text{ and } \\ \omega_{1}^{*} = \frac{\rho C_{e}c_{1}^{2}}{c_{1}}. \tag{11}$$

To relate the displacement components to the two potential functions ψ_1 and ψ_2 use the expression

$$u = \frac{\partial \psi_1}{\partial x} + \frac{\partial \psi_2}{\partial y} \text{ and } v = \frac{\partial \psi_1}{\partial y} - \frac{\partial \psi_2}{\partial x}.$$
 (12)

To get the exact solution without any approximation for the physical quantities, consider the solution in the form of the normal modes as

$$[\psi_1, \psi_2, \phi, \theta](x, y, t) = [\psi_1^*, \psi_2^*, \phi^*, \theta^*](y) \exp\{i(ax - \xi t)\},$$
(13)

Where, $[\psi_1^*, \psi_2^*, \phi^*, \theta^*](y)$ are the amplitude of the physical quantities, ξ is the angular frequency, $i = \sqrt{-1}$ and *a* is the wave number in the *x* - direction.

Eqs. (7)-(10), with the help of the Eqs. (11)-(13) after dropping primes for convenience

$$[D^{2} - m_{2}] \psi_{1}^{*} - m_{3} \psi_{2}^{*} + m_{4} \phi^{*} - m_{5} \theta^{*} = 0,$$

$$(14)$$

$$m_{6} \psi_{1}^{*} + [D^{2} - m_{7}] \psi_{2}^{*} = 0,$$

$$(15)$$

$$-a_{c}\left[D^{2}-a^{2}\right]w_{*}^{*}+\left[D^{2}-m_{c}\right]\phi^{*}+a_{c}\theta^{*}=0$$
(16)

$$m_{10}[D^2 - a^2]\psi_1^* + m_{11}\phi^* + [D^2 - m_{12}]\theta^* = -Sf(x,t)e^{-\gamma y}.$$
(17)

Where,
$$m_2 = a^2 - (a_5 \xi^2 / m_1)$$
, $m_3 = (i a a_4 / m_1)$, $m_4 = a_2 / m_1$, $m_5 = a_3 / m_1$, $m_6 = i a a_4$, $m_7 = a^2 - a_5 \xi^2$, $m_8 = a^2 + a_7 - i a_8 \xi - a_{10} \xi^2$, $m_9 = \varepsilon_3 - i \xi \varepsilon_2$, $m_{10} = \varepsilon_1 \xi^2 / m_9$, $m_{11} = i \xi a_{11} / m_9$, $m_{12} = a^2 - (\xi^2 / m_9)$, $S = Q_0 / m_9$, $f(x,t) = (1 - t/t_0) \exp\{(-x^2 / r^2) - (t/t_0) - (i a x) + (i \xi t)\}$, $Q_0 = I_0 \gamma / 2\pi r^2 t_0^2$, $D = d/dy$, $a_1 = \frac{\lambda_1 + \mu_1}{\mu_1}$, $a_2 = \frac{b_1 c_1^2}{a_1^2 \gamma_1 \mu_1}$, $a_3 = \frac{\beta_1 T_0}{\mu_1}$, $a_4 = \frac{\rho g c_1^2}{\mu_1 f(T)}$,



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 $a_{5} = \frac{\rho c_{1}^{2}}{\mu_{1} f(T)}, \quad a_{6} = \frac{b_{1} \psi_{1}}{\alpha_{1}}, \quad a_{7} = \frac{\xi_{11} c_{1}^{2}}{\alpha_{1} \omega_{1}^{*2}}, \quad a_{8} = \frac{\omega_{0} c_{1}^{2}}{\alpha_{1} \omega_{1}^{*}}, \quad a_{9} = \frac{m_{1} T_{0} \psi_{1}}{\alpha_{1}}, \quad a_{10} = \frac{\rho c_{1}^{2} \psi_{1}}{\alpha_{1}}, \quad a_{11} = \frac{m_{1} f(T) c_{1}^{2}}{\rho C_{e} \psi_{1} \omega_{1}^{*3}}, \quad \varepsilon_{1} = \frac{\beta_{1} f(T)}{\rho C_{e}}, \quad \varepsilon_{2} = \frac{k^{*} \omega_{1}^{*}}{\rho C_{e} c_{1}^{2}}, \quad \varepsilon_{2} = \frac{k^{*} \omega_{1}^{*}}{\rho C_{e} c_{1}^{2}}, \quad \varepsilon_{3} = \frac{\beta_{1} f(T)}{\rho C_{e} (T)}, \quad \varepsilon_{4} = \frac{\beta_{1} f(T)}{\rho C_{e} (T)}, \quad \varepsilon_{5} =$ $\varepsilon_3 = \frac{k}{\rho C_e c_1^2}, \ m_1 = a_1 + 1.$

Eliminate the functions ψ_1^* , ψ_2^* , ϕ^* and θ^* between equations (14)-(17), to obtain the differential equations

$$[D^{8} - \lambda_{1} D^{6} + \lambda_{2} D^{4} - \lambda_{3} D^{2} + \lambda_{4}] \psi_{1}^{*} = -S A_{1} f(x, t) \exp(-\gamma y),$$

$$[D^{8} - \lambda_{1} D^{6} + \lambda_{2} D^{4} - \lambda_{3} D^{2} + \lambda_{4}] \psi_{2}^{*} = -S A_{2} f(x, t) \exp(-\gamma y),$$
(18)
(19)

$$[D^{8} - \lambda_{1} D^{6} + \lambda_{2} D^{4} - \lambda_{3} D^{2} + \lambda_{4}] \psi_{2}^{*} = -S A_{2} f(x, t) \exp(-\gamma y),$$
(19)

$$[D^{8} - \lambda_{1}D^{6} + \lambda_{2}D^{4} - \lambda_{3}D^{2} + \lambda_{4}]\phi^{*} = -SA_{3}f(x,t)\exp(-\gamma y), \qquad (20)$$

$$[\mathbf{D}^{8} - \lambda_{1}\mathbf{D}^{6} + \lambda_{2}\mathbf{D}^{4} - \lambda_{3}\mathbf{D}^{2} + \lambda_{4}]\theta^{*} = -SA_{4}f(x,t)\exp(-\gamma y).$$

 λ_n (n = 1, 2, 3, 4) and A_n (n = 1, 2, 3, 4) can be obtained from elimination the functions from Eqs. (14)-(17). Equation (21) factored as

$$(\mathbf{D}^{2} - k_{1}^{2})(\mathbf{D}^{2} - k_{2}^{2})(\mathbf{D}^{2} - k_{3}^{2})(\mathbf{D}^{2} - k_{4}^{2})\theta^{*} = -SA_{4}f(x,t)\exp(-\gamma y),$$
(22)

 k_n^2 (n = 1, 2, 3, 4) are the roots of the characteristic equation of the homogeneous equation of Eqs. (18)-(21). The general solution of the considered physical quantities which is bounded as $y \rightarrow \infty$, is given by

$$u(x, y, t) = \sum_{n=1}^{4} L_{ln} R_n \exp\{-k_n y - i(\xi t - ax)\} - ((2A_1 x / r^2) + \gamma A_2) B_1 Q_1 \exp(-\gamma y),$$
(23)

$$v(x, y, t) = \sum_{n=1}^{4} M_{\ln} R_n \exp\{-k_n y - i(\xi t - ax)\} + (-\gamma A_1 + (2xA_2/r^2))B_1 Q_1 \exp(-\gamma y),$$
(24)

$$\phi(x, y, t) = \sum_{n=1}^{4} C_{2n} R_n \exp\{-k_n y - i(\xi t - ax)\} + A_3 B_1 Q_1 \exp(-\gamma y),$$
(25)

$$\theta(x, y, t) = \sum_{n=1}^{4} C_{3n} R_n \exp\{-k_n y - i(\xi t - ax)\} + A_4 B_1 Q_1 \exp(-\gamma y),$$
(26)

$$\sigma_{yy}(x, y, t) = \sum_{n=1}^{4} C_{5n} R_n \exp\{-k_n y - i(\xi t - ax)\} + B_3 B_1 Q_1 \exp(-\gamma y),$$
(27)

where
$$C_{1n} = -m_6/(k_n^2 - m_7)$$
, $C_{2n} = \{a_6m_5(k_n^2 - a^2) + a_9m_3C_{1n} - a_9(k_n^2 - m_2)\}/\{m_5(k_n^2 - m_8) + a_9m_4\}$, $C_{3n} = \{a_6m_5(k_n^2 - m_2) - m_3C_{1n} + m_4C_{2n}\}/m_5$,
 $C_{5n} = a_{12}(iaL_{1n} - k_nM_{1n}) - 2a_{13}k_nM_{1n} + a_{14}C_{2n} - a_{15}C_{3n}$, $B_1 = -1/\{\gamma^8 - \lambda_4\gamma^6 + \lambda_2\gamma^4 - \lambda_3\gamma^2 + \lambda_4\}$, $Q_1 = Sf_1(x,t)$, $f_1(x,t) = (1 - t/t_0)\exp\{(-x^2/r^2) - (t/t_0)\}$,
 $B_3 = a_{12}[\frac{2}{r^2}\{A_1(1 - (\frac{2x^2}{r^2})) - x\gamma A_2\} - \gamma(-\gamma A_1 + \frac{2xA_2}{r^2}))] - 2a_{13}(-\gamma A_1 + \frac{2xA_2}{r^2}) + a_{14}A_3 - a_{15}A_4$, $a_{12} = \frac{\lambda_1 f(T)}{\mu_1}$, $a_{13} = f(T)$, $a_{44} = \frac{b_4c_1^2 f(T)}{\mu_1 \mu_1^{42}}$, $a_{15} = \frac{\beta_1 T_0 f(T)}{\mu_1}$,
 $L_{1n} = (ia - k_n C_{1n})$, $M_{1n} = -(k_n + ia C_{1n})$, $n = 1, 2, 3, 4$.

Since, R_n (n = 1, 2, 3, 4) are constants (the coefficients of the series).

III. APPLICATIONS

Consider the following non-dimensional boundary conditions to determine the coefficients R_n (n = 1, 2, 3, 4) and suppress the positive exponentials to avoid the unbounded solutions at infinity. Then the surface of the solid at y = 0assumes these conditions

(1) The mechanical boundary conditions are

(i) The normal stress condition (mechanically stressed by constant force p_1), so that

$$\sigma_{yy} = -p_I e^{i(ax - \xi t)}, \tag{28}$$

(ii) The tangential stress condition (stress free), then

$$\sigma_{xy} = 0,$$

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(2) The condition of the voids (the volume fraction field is constant in y-direction). This implies that

$$\frac{\partial \phi}{\partial y} = 0,$$

(3) The thermal condition (the half-space is a thermally insulated boundary).

$$\frac{\partial \theta}{\partial y} = 0. \tag{31}$$

Substituting the expressions of the considered quantities in these boundary conditions, to obtain the equations satisfied by the parameters. Then one can obtain a system of four equations. After applying the inverse of matrix method, we get the values of the constants R_n (n = 1, 2, 3, 4).

$$\begin{pmatrix} R_1 \\ R_2 \\ R_3 \\ R_4 \end{pmatrix} = \begin{pmatrix} C_{51} & C_{52} & C_{53} & C_{54} \\ C_{61} & C_{62} & C_{63} & C_{64} \\ -k_1 C_{21} - k_2 C_{22} - k_3 C_{23} - k_4 C_{24} \\ -k_1 C_{31} - k_2 C_{32} - k_3 C_{33} - k_4 C_{34} \end{pmatrix} \begin{pmatrix} -p_1 \\ 0 \\ 0 \\ 0 \end{pmatrix}.$$
(32)

Hence, obtain the expressions for the physical quantities of the plate surface.

IV. PARTICULAR CASES

- (i) In the case of absence of the gravity: taking g = 0 in equation (1).
- (ii) In the case of absence of the temperature dependent properties: taking $\alpha^* = 0$ in the relations
- (iii) In the case of the absence of the porous: taking $\alpha, b, \xi_1, \omega_0, m$ and $\psi = 0$ in Eqs. (1)-(4).

V. NUMERICAL RESULTS AND DISCUSSION

Following Dhaliwal and Singh [19], the porous magnesium crystal-like thermoelastic solid chosen to evaluate the numerical results. All the units of parameters used in the calculation given in SI units. The constants of the problem taken as

$$\begin{split} \lambda &= 2.17 \times 10^{10} N \ / m^2, \ \mu &= 3.278 \times 10^{10} N \ / m^2, \ k &= 1.7 \times 10^2 W \ / m \cdot K, \ C_e &= 1.04 \times 10^3 J \ / kg \cdot K, \ \rho &= 1.74 \times 10^3 kg \ / m^3, \ \beta &= 2.68 \times 10^6 N \ / m^2 \cdot K, \\ \omega_1^* &= 3.58 \times 10^{11} \ / s, \ \alpha_t &= 1.78 \times 10^{-5} N \ / m^2, \ T_0 &= 298 \ K, \ \psi &= 1.753 \times 10^{-15} m^2, \ \alpha &= 3.688 \times 10^{-5} N, \ \xi_1 &= 1.475 \times 10^{10} N \ / m^2, \ g &= 9.8 \ m \ / s^2, \\ b &= 1.13849 \times 10^{10} N \ / m^2, \ m &= 2 \times 10^6 N \ / m^2 \cdot K, \ \omega_0 &= 0.0787 \times 10^{-3} N \ / m^2 \ s, \ I &= 10 \ J \ / m, \ r &= 10 \ \mu \ m, \ \gamma &= 50 \ / m, \ t &= 4 \ n \ s, \ p_1 &= 1.5 \ N \ / m^2, \\ k^* &= 85 \ W \ / m \cdot K, \ a &= 1.6 \ m, \ \xi &= \eta + i \eta_1, \ x &= 10 \ m, \ \eta &= 0.1 \ rad \ / s, \ \eta_1 &= 5.5 \ rad \ / s, \ t &= 0.01 \ s, \ 0 &\leq y &\leq 2 m. \end{split}$$

These numerical values were used for the variation of the real parts of the displacement, the temperature, the stress and change in the volume fraction field. Figs. 1-13 are graphically represented changes in the behavior of the physical quantities against distance y in 2D for the (G-N) theory of both types II and III in the presence and absence of the gravity effect (g = 9.8,0) during $\alpha^* = 0.00051$, the temperature dependent ($\alpha^* = 0.00051,0$) during g = 9.8, in the presence and absence of the porous effect on the solid. Figs. 1-4 represent the variation of the considered physical quantities in the case of the absence and the presence of the gravity since the other effects are present. Figs. 5-8 determine the variation of the considered physical quantities in the case of the absence and the presence of the absence and the other effects are present. In the obtained figures, the solid and dashed lines represent the solutions in the context of the (G-N) theory of type II and the lines with dots represent the derived solutions using (G-N) theory of type III. Fig. 1 shows the variation of the displacement u in the case of g = 9.8, 0; it noticed that the variation of u is increasing in the case of both types II and III of (G-N) theory for y > 0, with the increase of the value



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Fig. 3 depicts the variation of σ_{yy} is increasing for both types II and III of (G-N) theory with the increase of g for y > 0. Fig. 4 expresses the variation of ϕ is decreasing with the increase of the value of g for y > 0 in both types II and III of (G-N) theory with the increase of the value of g for y > 0. It is clear that the gravity has an important role in the variation of the physical quantities. Fig. 5 shows the variation of the displacement u in the case of $\alpha^* = 0.00051, 0$; it noticed that the variation of u is increasing in the case of (G-N) theory of both types II and III for y > 0 with the increase of the value of α^* . Fig. 6 clarifies the variation of θ is increasing for types II and III of (G-N) theory with the increase of the temperature dependent properties for y > 0. Fig. 7 depicts the variation of σ_{yy} for $\alpha^* = 0.00051, 0$; it is noticed that the variation of σ_{yy} is decreasing for both types II and III of (G-N) theory with the increase of α^* for y > 0. Fig. 7 depicts the variation of σ_{yy} for $\alpha^* = 0.00051, 0$; it is noticed that the variation of σ_{yy} is decreasing for both types II and III of (G-N) theory with the increase of α^* for y > 0 with the increase of α^* value.



Fig. 8 expresses the variation of ϕ is decreasing with the increase of the value of α^* for y > 0 in both types II and III of (G-N) theory. It deduced that the temperature dependent properties have a significant role in the variation of the physical quantities.



Fig. 5 Variation of u with and without the temperature dependent









Fig. 7 Variation of σ_{yy} with and without the temperature dependent Fig. 8 Variation of ϕ with and without the temperature dependent



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Fig. 9 shows the variation of the displacement u in the case of the absence and the presence of the laser pulse effect; it noticed that the variation of u is increasing in both types II and III of (G-N) theory for y > 0 with the increase of the laser pulse value of the porous thermoelastic solid. Fig. 10 expresses the variation of σ_{yy} in the case of the absence and the presence of the laser pulse effect; it observed that the variation of σ_{yy} is increasing in both types II and III of (G-N) theory for y > 0 with the increase of the absence and the presence of the laser pulse effect; it observed that the variation of σ_{yy} is increasing in both types II and III of (G-N) theory for y > 0 with the increase of the laser pulse value of the porous thermoelastic solid.



Fig. 9 Variation of u with and without the laser pulse effect

Fig. 10 Variation of σ_{yy} with and without the laser pulse effect

Fig. 11 clarifies the variation of ϕ in the case of the absence and the presence of the laser pulse effect; it observed that the variation of ϕ is decreasing in both types II and III of (G-N) theory for y > 0 with the increase of the laser pulse value on the porous thermoelastic solid. It deduced that the presence of the laser pulse effect is a significant in the variation of the physical quantities. Fig. 12 shows the variation of the displacement *u* in the case of the absence and the presence of the porous effect; it noticed that the variation of *u* is decreasing in both types II and III of (G-N) theory for y > 0 with the increase of the porous existence on the thermoelastic solid.



Fig. 11 Variation of ϕ with and without the laser pulse effect

Fig. 13 clarifies the variation of θ in the case of the absence and the presence of the porous effect; it observed that the variation of θ is increasing in both types II and III of (G-N) theory for y > 0 with the increase of the porous existence on the thermoelastic solid. It deduced that the presence of the porous effect is a significant in the variation of the physical quantities. All the previous functions are continuous and all curves converge to zero.



Fig. 12 Variation of u with and without the porous effect



Fig. 13 Variation of θ with and without the porous effect



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3D curves are representing the complete relation between physical quantities u and σ_{xy} with both components of the distance as shown in Figs. 14-15, in the presence of the gravity, the temperature dependent properties and the effect of the porous in the studied thermoelastic solid in the context of (G-N) theory of type III. 3D figures stated that all the physical quantities are moving in the wave propagation.



Figs. 14, 15 respectively 3D Curve of variation of u and σ_{xy} versus the components of distance

IV. CONCLUSIONS

The gravity and the temperature dependent properties have a significant effect on the variation of the considered physical quantities, since they make great changes in the behaviour of the functions, also the same observation of the absence and the presence of the porous and the laser pulse effect in the thermoelastic solid. The laser pulse heating effect is an important thermal loading in many scientific uses as the biological and the geological treatments of the materials. These physical quantities are continuous functions and all the curves converge to zero, as the solution using the normal mode method gives the exact solutions of the functions.

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