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BraTS : Brain Tumor Segmentation – Some Contemporary Approaches

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ABSTRACT: Brain tumor is nothing but the abnormal growth of cancerous cells within Brain. In medical field, segmentation of brain regions & detection of brain tumor is very challenging task because of its complex structure. Magnetic resonance imaging (MRI) provides the detailed information about brain anatomy. Proper brain tumor segmentation using MR brain images helps in identifying exact size & shape of Brain tumor, this intern helps in diagnosis & treatment of brain tumor. Detection of brain tumor from MRI images involves various steps such as MR image pre-processing, segmentation of image & feature extraction. Proposed paper explains about the methods that use Histogram Thresholding, K-means clustering, and Fuzzy C- Means & Support Vector Machine (SVM). Presented method includes several steps such as pre-processing; high frequency components and noise are removed & RGB to gray conversion, global image threshold; converts intensity image into binary image, erosion & dilation of binary image to locate tumor exactly, detecting the stage of the tumor whether Benign or Malignant.

KEYWORDS: Brain tumor, Magnetic resonance imaging (MRI), Histogram Thresholding K-Means clustering, FCM & SVM, Neural Network.

I. INTRODUCTION

Brain is one of the complex organ in human body as it contains 50-100 billion neurons in it forming a network. Brain tumors are classified as Benign Brain tumor and malignant brain tumor based on the type of tissue present in involved in formation of tumor.

Benign Brain tumor: - Benign Brain tumor normally does not contain any cancer causing cells & it doesn't affect the nearby healthy tissues. These cells can be removed by surgery.

Malignant Brain tumor: - malignant Brain tumor contain cancer causing cells, these cells grows very rapidly with the time & affect other nearby health brain tissues and cause severe problem, ultimately that may cause the death of the person.

From past few years Brain tumor segmentation becomes a very challenging research area in the medical field. Brain tumor segmentation helps in identifying exact size, shape & location of brain tumor. The segmentation experimented with magnetic resonance imaging (MRI) scanned images in proposed method [1]. Usually MRI scan & CT scan are used to view the anatomy of brain, but MRI scan is more convenient as compare to CT scan for diagnosis. [2], the K-Means clustering & fuzzy C-Means algorithms are used to detect the exact location of brain tumor. Using fuzzy C-means algorithm stage of patient's tumor is determined.

Moumen T El-Melegy and Hashim M Mokhtar proposed a new fuzzy approach to segment the brain MRI images, this approach is more accurate & faster than other fuzzy techniques [3]. Tumor is an abnormal growth mass of cancerous tissues, it's very important to detect the brain tumor. Segmentation of MR images of brain is very difficult task. [4], Swati Chawla&Nehagarg proposed a method using fuzzy C-means clustering & region growing that includes enhancement & segmentation deeply. In the first step noise & high frequency components are removed using filters & resultant images are used to detect the exact shape, size of the tumor. [5], includes a survey on different brain tumor



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segmentation techniques to locate tumor and fuzzy C-Means algorithm is proposed to segment the brain MR images, this is also used to calculate the tumor area this information helps to differentiate between type of brain tumor. The MRI of brain is normally diagnosed by physician to locate brain tumor, this detection method does not provides the accurate result. To overcome from this [6], project that produces accurate result & uses computer aided method to detect brain tumor. This intern reduces the consumption of time for diagnosis. Stage of the tumor can be calculated based on the amount of area computed from algorithm.

From past few years many brain tumor segmentation techniques are implemented to locate the brain tumor in MRI. Nowadays Image processing became a very important part of medical field. [7], includes survey on different brain tumor segmentation techniques such as fuzzy C-Means algorithm; this algorithm is used to detect area, size & shape of tumor, knowledge based algorithm; this technique uses multispectral histogram to differ tumor from other healthy parts of the brain, probabilistic neural network (PNN); it gives much accurate & faster result compare to other segmentation techniques. Clustering meant to be dividing the set of data into similar objects groups, groups includes objects of similar characteristics. Objects are grouped depending on some object (pixel) characteristics. K-Means clustering is most useful to divide mass of data quickly & efficiently, intern segmentation became easier. K-means clustering technique for brain tumor segmentation described, [8].

Most of the studies & survey in different countries proved that number of brain tumor patients died because of imprecise tumor detection. Brain tumor may be primary or secondary, it will be primary when tumor at origin stage & will be secondary when tumor cells starts spreading to other healthy tissues of brain. Both Primary & secondary brain tumor can be detected using method that uses K-Means clustering, [9]. [10], proposes histogram Thresholding & artificial neural network. Modification was done on previous segmentation methods to overcome from drawbacks; ROI (region of interest) parameter is used in diagnosis of MRI images. Noise is removed in pre-processing step using Gaussian filter. Edge detection carried out fallowed by ROI & Finally feature extraction is done.

II. RELATED WORK

Most commonly used algorithm is K-Means clustering in image segmentation techniques. Researchers made several efforts to improve efficiency and accuracy of K- Means clustering algorithm. [11], Presented method, Histogram Thresholding to detect and segment brain tumor. Knowledge of area of tumor helps in diagnosis & treatment of tumor. Manual segmentation of MRI is very stimulating & time consuming work. Histogram Thresholding method helps researcher to overcome from these drawbacks.

[12], Describes modified fuzzy c-means method for brain MRI image segmentation, it uses both local & non-local spatial context in order to decrease the noise in segmentation process. The FCM algorithm presented to overcome from the disadvantages of other previous segmentation techniques. In this FCM method both local and non-local information integrates into FCM clustering for better efficiency, method allows cataloguing of one pixel get prejudiced from another pixel and this algorithm suppresses the noise during segmentation procedure.Magnetic resonance imaging provides detailed anatomy of human tissue. Mathematical morphology is used in many applications like object segmentation boundary detection & to decrease noise effect, [13].

Region growing is one of the method to detect & classify the brain tumor. Commonly in region growing method pixel with same characteristics are put together. The characteristics or parameter is used to group pixel is intensity of pixel. One pixel intensity parameter is compared with neighbour pixel parameter & grouped. Similar parameter pixels are grouped together & continue segmentation. Region growing method have various steps such as 1).pre-processing; filter is used to remove noise & unwanted frequency components, RGB image is converted to grey scale image, 2).Apply modified region growing method, 3).feature extracted from image, 4).Classification done using Neural network method, [14]. Rambabu, C.H., & Siva ayyappakumar, B . Proposed a method which uses clustering algorithm based on intensity, PNN (probabilistic Neural Network) is implemented to classify different stages of tumor such as normal, Benign & Malignant. Uses two steps Grey scale conversion & Neural Network is used to classify, [15]. Grade of the tumor is classified using ANN (artificial Neural Network). Yashsharma, &Meghachhabra combines all the previous techniques researched for particular task to locate tumor accurately & for better efficiency, [16].



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III. PROPOSED METHODOLOGY

In this section, we proposed different brain tumor segmentation techniques such as Histogram Thresholding, k-means clustering, fuzzy c- means & support vector machine. This section addresses the difficulties in segmenting the brain tumor image because of its complexity and solution to overcome from those problems. These methods are implemented on set of datasets to check accuracy & efficiency.

A. HISTOGRAM THRESHOLDING

Histogram Thresholding is one of the most commonly used & simple technique in image segmentation field. Thresholding method replaces each pixel to black pixel if $\mathbf{I}_{I,J} < \mathbf{T}$, i.e. pixel intensity $\mathbf{I}_{I,J}$ less than that of fixed threshold value T and Thresholding replaces pixel with white pixel if $\mathbf{I}_{I,J}$ is greater than that of fixed threshold value Histogram means representation of numerical data in graphical form. Image histogram contains peaks & valleys. Histogram Thresholding has many steps such as pre-processing; RGB to grey conversion, Image is partitioned into two equal parts with central axis in histogram Thresholding, plot histogram for those parts & are compared to locate the tumor in MRI brain image, segmentation done using threshold point, Exact dimensions of brain tumor are detected by cropping method; cropping helps in getting the required part of the image, intern makes analysis easier, finally area of tumor is calculated. In Histogram Thresholding method gray image has the intensity value between 0-255, 0 for black pixel & 255 for white pixel.

B. K-MEANS CLUSTERING

K-means clustering is one of the unverified algorithms for clusters. Grouping of pixels based on some parameter is called clustering. We have to declare the number of clusters k in this algorithm, declared k clusters centers are selected randomly. Have to calculate the distance between each cluster & each pixel for further use. The distance between cluster & pixel is calculated using simple Euclidian function. First consider a pixel from an image & compare that pixel with all k- cluster centers by distance formula. After comparing, that pixel is shifted to some particular cluster among k- cluster which has shortest distance among all other clusters. This process continues for all other pixels until center meets or joins. Therefore k-means clustering function is used to cluster the data.Calculate Cluster for given image, from below equation (1).

$$M = \frac{\sum_{nc(i)} = k^{Xi}}{NC} (1) \qquad \text{Where } k = 1....K$$

Distance between each pixel & cluster given b	by equation (2).	
$D(i) = \arg \min X_i - MK ^2$	(2)	Where i=1N

C. FUZZY C-MEANS ALGORITHM

Dunn introduced the fuzzy c-means (FCM) clustering algorithm & it further improved by Bezdek. In fuzzy c-means algorithm a set of n-vectors are divide into c fuzzy groups & cluster center is found in each group so that dissimilarity is reduced. Fuzzy c-means algorithm is simple to implement & faster as compare to other segmentation techniques. FCM resist noise & can achieve efficient segmentation. In this algorithm partial membership is given to each pixel of the image. The range of membership value is between 0 & 1. Fuzzy c-means algorithm provides intermediate fuzzy values for each pixel i.e.in the same image one fuzzy set may be part of other fuzzy set, hence in FCM part of data is associated with more than one cluster.

In FCM noise is almost vanished by decreasing below objective function, i.e. equation (3).

$$J_m = \sum_{i=1}^N \sum_{j=1}^C u_{ij}^m ||x_i - c_j||^2$$
(3)

In equation (3),where m ranges between 1 & ∞ i.e. $1 \le m \le \infty$ m=real number(m>1)

 $u_{ij} = x_i$ membership degree in j cluster



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 $x_i = i^{th}$ measured data of d-dimensional

 C_i = center of d-dimensional cluster

D. SUPPORT VECTOR MACHINE

Support vector machine is one of the enhanced methods for classification of tumor from brain MR images. [17], oriented Rician noise reduction anisotropic diffusion filter is used in SVM method to remove noise. This method includes Digitization of image, removing noise from image using FCM (skull part is removed from the image), features are extracted using FCM algorithm, using joint entropy & genetic algorithm desired features are selected, and finally classification is done using SVM with kernels. The SVM classifier found more accurate with GRBF (Gaussian radial based functional) kernel. After classification the stage of the tumor is identified whether it is Benign or Malignant.

Fig.1. Explains how histogram Thresholding & fuzzy c-means works stepwise. Select input image, pre-processing; converts RGB to grey image & remove noise, segmentation procedure, this flowchart proposes two segmentation methods. Firstly the Histogram Thresholding; morphological operations are carried out & finally image is segmented to locate the tumor in MR images of brain. In FCM clustering is carried out to detect tumor efficiently compare to other clustering methods

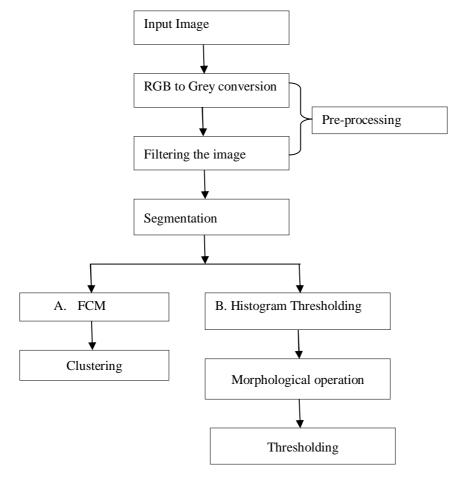


Fig.1. Flowchart for Fuzzy C-Means Clustering&Histogram Thresholding.



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IV. EXPERIMENTAL RESULTS & PERFORMANCE ANALYSIS

This section contains result of above explained segmentation methods. We verified set of datasets using histogram Thresholding, k-means, fuzzy c-means & support vector machine and got accurate & efficient results. Fig.2. shows result of Histogram Thresholding. Fig.3. shows result of k-means clustering. Fig.4. shows result of fuzzy c-means algorithm. Fig.5. shows result of SVM method. We compared output of all these methods with manually segmented images to check accuracy & got succeeded also. We can locate tumor very efficiently using these methods.

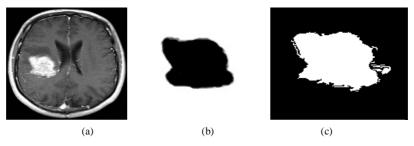


Fig. 2. Result of Histogram Thresholding, (a) Original Input Image, (b) Manually segmented brain MRI, (c) Output of Histogram Thresholding.

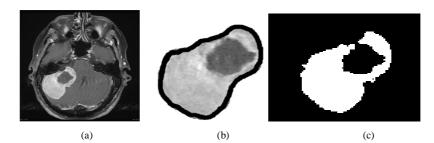


Fig.3. Result of k-means algorithm, (a) Original Input Image, (b) Manually segmented brain MRI, (c)k-means algorithm output.

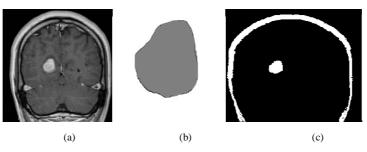


Fig. 4. Result of fuzzy c-means algorithm, (a) Original Input Image, (b) Manually segmented brain MRI, (c) fuzzy c-means algorithm output.



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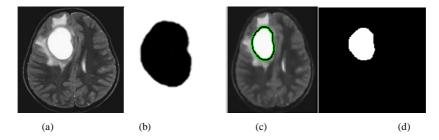


Fig. 5.Result of SVM method, (a) Original Input Image, (b) Manually segmented brain MRI, (c) SVM classifier, (d) Segmented image.

VI. CONCLUSION

Several methods discussed in the Introduction & related work, failed due to inaccuracy in locating tumor. Based on research & survey, number of brain tumor patients died because of imprecise brain tumor location. Hence it's very important to locate brain tumor exactly. Using proposed methods in this paper tumor is located & identified accurately, intern helps in differentiating stage of the tumor (benign or malignant). Every method segmented output is compared with manually segmented images and found more accurate. Proposed methods help in proper treatment of tumor by locating tumor accurately.

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