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Performance Analysis of TEG Based Solar PV System and Implementation of Hill Climbing MPPT Algorithm for Efficient Solar Water Pumping System

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ABSTRACT: This paper proposes the new Thermoelectric Generator based solar photovoltaic system for water pumping application. Thermoelectric power generation has emerged as a promising alternative green technology for the power generation from waste heat. Thermoelectric device generates voltage and electrical power from waste heat to electronic load by means of the temperature difference across solar panel and the atmosphere. To achieve maximum power input to the motor-pump setup, Hill climbing Algorithm is used. It starts with measuring the present values of the PV array voltage and current . Therefore, the generated power can be calculated and compared to its value calculated in the previous iteration. According to the result of comparison; the sign of a 'slope' is either complemented or remains unchanged and the PWM output duty cycle is changed accordingly. The power generated from the photovoltaic array is delivered to the load through a DC/ DC converter to control the output voltage of the solar panel and achieve a maximum energy extraction. This paper also presents the details of system design and analyses of its dynamic behavior during varying environmental conditions are verified using MATLAB simulation.

KEYWORDS: Thermoelectric Generator, Hill climbing Algorithm, maximum energy extraction.

I. INTRODUCTION

Solar power system finds extensive application in remote areas where access to the grid supply is impractical. From livestock watering to remote home or village water supply needs are met from the solar based water pumps. Most of the PV water pumping systems are connected directly to the solar arrays and use DC motor driven pumps [1]. This system is easy to operate but is inefficient and requires frequent maintenance. Solar pump operated with AC drive uses an inverter with ac motor. Induction motor offer better choice in terms of size, ruggedness, efficiency and maintainability.

The DC power from solar array is boosted and fed to an inverter which gives ac. Output of the inverter drives the motor coupled to a water pump. Photovoltaic power system usually requires maximum power point tracking (MPPT) controller, which is an electronic system that operates the Photovoltaic (PV) modules in a manner that allows the modules to produce all the power they are capable of. There are different types of MPPT algorithms like Fractional Order Extremum seeking, Fractional open circuit voltage method, incremental conductance method etc which can be grouped as traditional techniques.

Fractional open circuit voltage method finds the linear relationship between V_{mpp} and V_{oc} under varying irradiance and temperature levels. But V_{mpp} can be computed with measured V_{oc} by momentarily shutting down the power converter. This may lead to loss of power. Another MPPT method called incremental conductance uses two voltage and current sensors to sense the output voltage and current of PV array. This method used to calculate instantaneous conductance



(An ISO 3297: 2007 Certified Organization)

Vol. 5, Issue 5, May 2016

equals to the conductance of solar then MPP is reached. Cost and complexity of this method goes on increasing. Major dis advantage of this method is that it produce oscillations and perform erratically under rapidly changing atmosphere.

II. HILL CLIMBING MPPT ALGORITHM

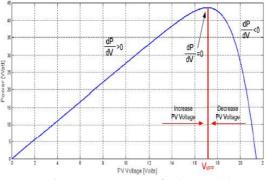


Figure.1 P-V curve of solar module

Figure-1 presents typical Power versus Voltage curve. Basic and simple operation of "Hill Climbing" algorithm is shown on this one. Red line represents that point where slope iszero and PV maximum power is extracted. When slope's signis positive a PV voltage increasing is essential in order to achieve operation in MPP. Similarly, a decreasing in PVvoltage must be done in the case of a negative slope's sign.Classic "Hill Climbing" algorithm can be operated both witha fixed and a variable voltage step change. During operationwith fixed voltage step size, there is no need to control the waythat step is changed. Otherwise, in operation with a variablevoltage step size it is necessary to find a way for controlling itflexibly.

New MPPT method that presented in this paper, is actually a modification of classic "Hill Climbing" one. According to this, any P - V slope's sign control and dynamic step size selection are avoided. The only thing that needs to be done is to calculate cube of P - V characteristic curve slope and add this to previous value of PV voltage. As shown on figure 3 (where x – axis represents slope and y – axis desirable voltage change) this modified algorithm is based on a hyperbola relation between slope and voltage step change. This kind of relation allows selection of bigger voltage step changes when slope is big, while step size is smaller as slope tends to be zero. When slope becomes zero there is no voltage change. In each calculation step cube of P - V curve's slope is calculated and result is added in previous PV voltage value VK. Through this procedure not only the desirable voltage changing direction, but also the appropriate voltage step change Vref are resulted. Thus, no control operation is essential and the whole system is forced to operate under new voltage VK+1.Following Figure-2 shows the flowchart of hill climbing algorithm.



(An ISO 3297: 2007 Certified Organization)

Vol. 5, Issue 5, May 2016

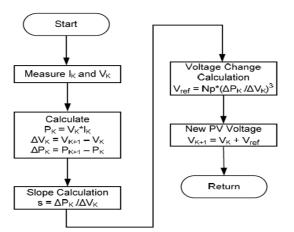


Figure.2 the flowchart of hill climbing algorithm

III THERMOELECTRIC GENERATOR

The direct conversion of solar heat to electrical energy can be achieved by means of thermoelectric generators (TEGs). TEGs work on the Seebeck effect. [2] Summarizes the different types of design according to the heat flow through the device and the layout of TCs. In lateral/lateral type the heat flow is lateral and the TCs layout is also lateral. In vertical/lateral type the heat flow is vertical and the TCs layout is also vertical. Thermal contact to heat source and sink is improved with a vertical design. This is because of the increased contact surface area. This increases the temperature difference between the hot and cold side. Since the output voltage is proportional to the temperature difference, voltage output increases and is considered for the experimental analysis.

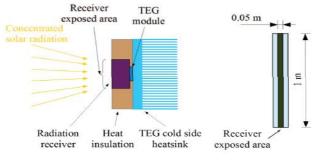


Figure.3 thermoelectric circuit

Figure-3 shows Thermoelectric generating circuit (TEG) that convert temperature differences into usable electricity. TEGs are made from thermoelectric modules which are solid-state integrated circuits that employ three established thermoelectric effects known as the Peltier, Seebeck and Thomson effects. TEGs require heat as an energy source and can generate power as long as there is a heat source such as gas or oil flame, stove, camp fire, industrial machinery, and furnace. Solar modules which convert light energy into usable electricity need direct sunlight to generate maximum rated power. Usually solar tracking systems are used to receive direct sun light to increase the efficiency of the modules. This type of setup increases the cost of the photovoltaic systems.

The use of TEGs based on thermoelectric effects (or Seebeck, Peltier, Thomson effect) is made possible by direct conversion of temperature differences to electrical power. The Seebeck effect occurs when a temperature difference exists between two dissimilar electrical conductors or semiconductors, producing a voltage across two materials.



(An ISO 3297: 2007 Certified Organization)

Vol. 5, Issue 5, May 2016

Thermal gradients in the environment are directly converted to electrical energy through the Seebeck (thermoelectric) effect Temperature changes between opposite segments of a conducting material result in heat flow and consequently charge flow since mobile, high-energy carriers diffuse from high to low concentration regions. Thermopiles consisting of n- and p-type materials electrically joined at the high-temperature junction are therefore constructed, allowing heat flow to carry the dominant charge carriers of each material to the low temperature end, establishing a voltage difference across the base electrodes in the process.

The generated voltage and power is relative to the temperature differential and the Seebeck coefficient of the thermoelectric materials. Big thermal gradients are essential to produce practical voltage and power levels .However, temperature differences greater than 10°C are rare in a micro-system, so consequently such systems generate low voltage and power levels. Moreover, naturally occurring temperature variations can also provide a means by which energy can be scavenged from the environment with high temperature. Stordeur and Stark have demonstrated a thermoelectric micro-device which is capable of converting 15 μ W/cm3 from 10 °C temperature gradients .While this is promising and, with the improvement of thermoelectric generators, could eventually result in more than 15 μ W/cm3, situations in which there is a static 10 °C temperature difference within 1 cm3 are very rare. This, however, assumes no losses in the conversion of power to electricity.

IV SOLAR WATER PUMPING SYSTEM

The drastic reduction in the cost of power electronic devices and annihilation of fossil fuels in near future invite to use the solar photovoltaic (SPV) generated electrical energy for various applications as far as possible. The water pumping, a standalone application of the SPV array generated electricity is receiving wide attention now a days for irrigation in the fields, household applications and industrial use.

The merits of both BLDC motor and zeta converter can contribute to develop a SPV array fed water pumping system possessing a potential of operating satisfactorily under dynamically changing atmospheric conditions. The BLDC motor has high reliability, high efficiency, high torque/inertia ratio, improved cooling, low radio frequency interference and noise and requires practically no maintenance [5-6]. On the other hand, a zeta converter exhibits following advantages over the conventional buck, boost, buck-boost converters and Cuk converter when employed in SPV based applications.

Belonging to a family of buck-boost converters, the zeta converter may be operated either to increase or to decrease the output voltage. This property offers a boundless region for maximum power point tracking (MPPT) of a SPV array. The MPPT can be performed with simple buck and boost converter if MPP occurs within prescribed limits.

This property also facilitates the soft starting of BLDC motor unlike a boost converter which habitually steps up the voltage level at its output, not ensuring soft starting. Unlike a classical buck-boost converter, the zeta converter has a continuous output current. The output inductor makes the current continuous and ripples free. Although consisting of same number of components as a Cuk converter, the zeta converter operates as non-inverting buck-boost converter unlike an inverting buck-boost and Cuk converter. This property obviates a requirement of associated circuits for negative voltage sensing hence reduces the complexity and probability of slow down the system response. These merits of the zeta converter are favorable for proposed SPV array fed water pumping system. An fractional order extremum seeking approach (FOESA) MPPT algorithm is used to operate the zeta converter such that SPV array always operates at its MPP.

Two phase currents are sensed along with Hall signals feedback for control of BLDC motor, resulting in an increased cost. The additional control scheme causes increased cost and complexity, which is required to control the speed of BLDC motor. Moreover, usually a voltage source inverter (VSI) is operated with high frequency PWM pulses, resulting in an increased switching loss and hence the reduced efficiency.Figure-4 shows the hardware implementation of BLDC based solar water pump.



(An ISO 3297: 2007 Certified Organization)

Vol. 5, Issue 5, May 2016



Figure.4 hardware implementation of BLDC based solar water pump.

VSIMULATIONS AND RESULTS

The simulation is done using MATLAB and the results are presented here.

A. Simulation Zeta Converter- Inverter System fed Induction Motor for P V Pumping.

The Simulink model of Zeta converter-inverter system for PV pumping fed induction motor is shown in Fig . The 12V DC input is boosted and converted to 230V AC using three-phase inverter. The switches of inverter operate at a high frequency of 20 kHz. This 230V, 20 kHz AC is converted to 400V DC. Another converter stage is required to reduce the frequency. As the 3phase inverter switches operates at 50 Hz, it converts 400V DC to 500V, 50 Hz AC which can be fed to the induction motor. The output voltage waveform of zeta converter- inverter system for PV pumping fed induction motor is shown in Figure.5

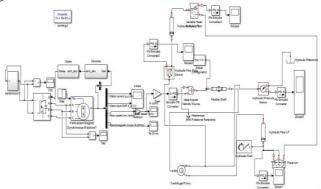


Figure.5 Simulation of BLDC based solar pumping system

BLDC water pumps in general use one-third to one-half the energy of conventional AC (alternating current) pumps. BLDC pumps areclassed as either displacement or centrifugal, and can be either submersible or surfacetypes. Displacement pumps use diaphragms, vanes or pistons to seal water in a chamberand force it through a discharge outlet.Centrifugal pumps use a spinning impeller that adds energy to the water and pushes into the system, similar to a water wheel.Submersible pumps, placed down a well or sump, are highly reliable because they are not exposed to freezing temperatures, do not needspecial protection from the elements, and donot require priming. Surface pumps, located ator near the water surface, are used primarily for moving water through a pipeline. Some surface pumps can develop high heads and aresuitable for moving water long distances or to high elevations. The simulation waveform have been shown in figure-6.



(An ISO 3297: 2007 Certified Organization)

Vol. 5, Issue 5, May 2016

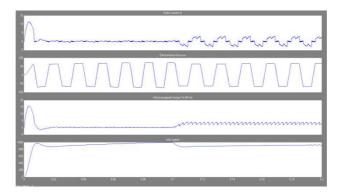
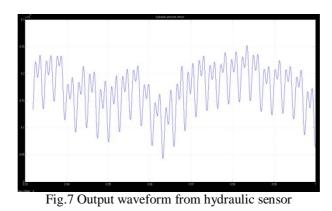


Figure.6 Output waveform from BLDC Motor

This purpose built motor is the result of years of research and development by the engineering staff at Mono. Specifically designed for use in solar pumps, this high torque motor is extremely efficient, the motor is fully sealed and oil filled. This design allows for an extremely long life in the hardest of applications. There are no brushes to wear out, therefore no maintenance



The above figure 7 shows the output waveform of hydraulic sensor, A pressure sensor measures pressure, typically of gases or liquids. Pressure is an expression of the force required to stop a fluid from expanding, and is usually stated in terms of force per unit area.

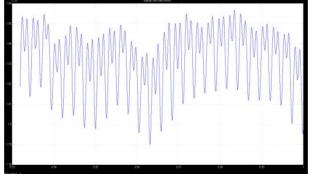


Fig.8 Output waveform from hydraulic flow rate sensor



(An ISO 3297: 2007 Certified Organization)

Vol. 5, Issue 5, May 2016

The above figure shows the output waveform of hydraulic flow rate sensor, A flow sensor is a device for sensing the rate of fluid flow. Typically a flow sensor is the sensing element used in a flow meter, or flow logger, to record the flow of fluids. As is true for all sensors, absolute accuracy of a measurement requires a functionality for calibration.

VI. CONCLUSION

This paper has evaluated the analysis of Photovoltaic cells and BLDC based water pumping system. Analysis, modelling and design of zeta converter with LC filter are also presented. The selection criteria of electric drive for photovoltaic pumping are elaborated. The 3 phase inverter in 180 and 120 mode operations is simulated. It is observed that the 180 mode is superior to 120 mode of operation. Common mode voltage is measured and it is observed that the common mode noise is reduced by using LC filter. The closed loop system is successfully modelled and simulated using the blocks of Simulink. The simulation results are in line with the predictions.

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(An ISO 3297: 2007 Certified Organization)

Vol. 5, Issue 5, May 2016

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