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# **Optimal Positioning and Sizing of DG Units Using Differential Evolution Algorithm**

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**ABSTRACT:** During the recent years, there has been a significant change in the power industry on power distribution systems mainly because of the introduction of smart-grid technology and the incremental use of distributed generation. Distributed Generation (DG) is simply refers to power generation at the point of consumption by placing smaller generating units, usually ten mega-watts or smaller. The distribution power system is designed generally for radial power flow, but with the onset of DG, bidirectional power flow becomes possible. The presence of DG on the distribution system also creates some potential problems related to safety, reliability, stability and security of the electrical system. DG on a power system affects the power flow, voltages, short circuit currents, losses and also other results. The impact of DG on the system, is whether positive or negative, will depend on the location and the size of the DG used This dissertation focuses on testing various indices relating to this and effective methodologies to find optimal size and placement of the DG unit which helps in reducing voltage deviation and power losses. The test system used here is IEEE 14 bus radial distribution system. The fast and feasible execution for the placement of DG is obtained with the optimization technique as desired. We have used Differential Evolution as Optimization technique; the results of which are compared with already implemented test system using NSGA algorithm. Comparative results show improved voltage profile and reduction in losses.

KEYWORDS: Distribution Generation (DG), Differential Evolution (DE)

### I. INTRODUCTION

Recently, increasing the energy consumption, the new transmission lines restriction, the steady progress in the power deregulation, and utility limitation have created growing interest in distributed power generation systems. In addition, improving voltage profile and reliability, reducing power losses and on-peak operating costs are the other salient factors which cause the tendency to utilize distributed generation (DG) units. [3] Distributed generators are beneficial in reducing the losses effectively compared to other methods of loss reduction. The challenge of identifying the optimal locations and sizes of DG has generated research interests all over the world and many efforts have been made in this direction. Studies have indicated that inappropriate locations and sizes of DG may lead to higher system losses than the ones in the existing network. [18]. Voltage variation and harmonic distortion are two major disturbances in distribution systems. The voltage drop occurs because of increasing electricity demand, thereby indicating the need to upgrade the distribution system infrastructure. To mitigate voltage variation and harmonic distortion in distribution systems, several strategies were applied, such as the use of passive and active power filters to mitigate harmonic distortion and the application of custom power controllers to mitigate voltage variation problems. However, these mitigation strategies require investment. Therefore, to improve voltage profile and eliminate harmonic distortion in a distribution system with DG, a noninvasive method is proposed, which involves appropriate planning of DG units and determining optimal placement and sizing of DG units. [9] The power flow algorithms have been used for determination of optimal positioning but in case of complex system, this method increases the complexity to unresolved



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level. Meta-heuristic algorithms came into existence then, their iteration process made the mitigation of voltage and harmonic deviation. This proposed method is tested on a 14-bus IEEE test system.



#### **II. PROBLEM FORMULATION**

The objective of the optimal size and location of DG problem to minimize the total power loss and voltage profile can be expressed as:

 $\begin{aligned} & \text{Minimize } P_L = \sum_{i=1}^N \sum_{j=1}^N \left[ \alpha_{i,j} (P_i P_j + Q_i Q_j) \right] + \beta_{i,j} (Q_i P_j - P_i Q_j) \\ & P_i Q_j) \end{aligned} \tag{1}$   $& \text{Where;} \end{aligned}$ 

 $\alpha_{i,j} = \frac{r_{i,j}}{V_i V_j} \cos(\delta_i - \delta_j)$  $\beta_{i,j} = \frac{r_{i,j}}{V_i V_j} \sin(\delta_i - \delta_j)$  $z_{i,j} = r_{i,j} + jx_{i,j}$ Where;  $z_{i,i}$  = between bus i and bus j line impedance;  $r_{i,j}$  = between bus i and bus j line resistance;  $\mathbf{x}_{i,i}$  = between bus i and bus j line reactance;  $V_i$  = bus i voltage magnitude;  $V_j$  = bus j voltage magnitude; Constraints: The objective function in (1) is subjected to the following constraints. (a) Bus voltage limits:  $V_{imin} \le V_i \le V_{imax}$ (2)Where;  $V_{imax}$  and  $V_{imin}$  = maximum and minimum voltage limits of i<sup>th</sup> node respectively.  $V_i$  = voltage at i<sup>th</sup> node. (b) Feeder capacity limits: Power flow in each branch must be less than or equal to its maximum capacity as given below.  $|\mathbf{I}_i| \leq \mathbf{I}_{imax}$ (3)Where  $I_{imax} = maximum$  current capacity of ith branch.  $I_i = current in i<sup>th</sup> branch$ 



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### III. SENSITIVITY ANALYSIS

#### 1. Loss Sensitivity Analysis

Sensitivity factor method is worked on the technique in which original non-linear equation is linearized around the initial point of operation, with the help of which solution space is reduced. Capacitor allocation problem is solved mainly using Loss sensitivity method. "Exact Loss" formula is used to provide real power loss in the system. The real power loss sensitivity factor with respect to real power injection is obtained by differentiating exact loss formula w.r.t. real power injection at bus Pi which is given by:

$$\alpha_i = \frac{\partial P_i}{\partial P_j} = 2 \sum_{j=1}^{N} [\alpha_{i,j}(P_j)] - \beta_{i,j}(Q_j)$$

At each bus Sensitivity factors are analyzed, firstly by using the values obtained at base case load flows. To form a priority list decreasing order of the buses according to the sensitivity factor values are arranged. Against injected power, the total power loss gives a parabolic function and when the losses are at minimum, the rate of change of real power loss w.r.t. real power injection becomes zero.

$$\alpha_i = \frac{\partial P_i}{\partial P_j} = 2 \sum_{j=1}^{N} \left[ \alpha_{i,j} (P_j) \right] - \beta_{i,j} (Q_j) = 0$$

which follows that,

$$P_i = \frac{\partial P_i}{\partial P_j} = \frac{1}{\alpha_{ii}} \left[ \beta_{i,i}(Q_i) + \sum_{j=1}^N \left[ \alpha_{i,j}(P_j) \right] - \beta_{i,j}(Q_j) \right]$$

where  $P_i$  gives at node i the real power injection, which is provided by subtracting real power demand and real power generation at that node.

 $P_i = P_{DGi} - P_{Di}$ 

where  $P_{DGi}$  represents real power injection from DG present on node i,  $P_{Di}$  is the load demand at node i, combining above equations we get

$$P_{i} = P_{Di} + \frac{1}{\alpha_{ii}} \left[ \beta_{i,i}(Q_{i}) + \sum_{j=1}^{N} \left[ \alpha_{i,j}(P_{j}) \right] - \beta_{i,j}(Q_{j}) \right]$$

The above equation determines the size of the DG at which the losses are minimum. By arranging the list in ascending order, the bus stood in the top is ranked as the first location of DG and further the process is repeated by placing the concerned size of DG at that particular location which generates the next location of DG. The process is said to be terminated when it determines the same location.

#### 2. Bus Sensitivity Analysis

Another method for reducing the search space is bus voltage sensitivity analysis. In this case each bus is penetrated at a time. After putting DG at each node its voltage sensitivity index can be calculated by equation. When DG is connected at bus I, voltage sensitivity index for bus i is given by:

$$BVSI = \sqrt{\frac{\sum_{k=1}^{N} (1 - V_k)^2}{N}}$$

where  $\dot{V}_k$  is the voltage at  $k^{th}$  node and N is the number of nodes. The node with the least BVSI will be chosen for DG placement.

#### **IV. DIFFERENTIAL EVOLUTION**

In evolutionary computation, differential evolution (DE) is a method in which a problem is optimized by improving the candidate solution which are compared to the given quality measure. These methods are normally called as metaheuristics as the assumptions made by them about the problem being optimized are few or no, and a very large space of candidate solutions are searched by them. However, it is also found that meta-heuristics such as DE does not always



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assure an optimal solution in every case. DE is used for multidimensional real-valued functions but does not use the gradient of the problem being optimized, which means it is not required that the problem has to be differential in case of DE as is needed in classic optimization methods such as gradient descent methods and quasi-newton method. On optimization problems that are not even continuous, are noisy, change over time, etc DE can be used.

In DE, a population of candidate solutions is maintained to optimize a problem and creating new candidate solutions with the help of combining available ones according to its simple formulae, and after that whichever candidate solution will have the best fitness or score on the optimization problem is kept. In this way the optimization problem acts as a black box which only provides a quality measure of provided candidate solution and therefore gradient is not needed.

Storn and Price originally introduced DE. Books are published on practical and theoretical aspects of using DE in parallel computing, multi objective optimization, constrained optimization, and the surveys of application areas are also contained in the books.

### V. ALGORITHM FOR FINDING DG SIZING USING DE

The algorithm for DG location and sizing can be given as:

Step 1: Run load flow for base case.

Step 2: Find the Bus voltage sensitivity indices at each node using equation

$$BVSI = \sqrt{\frac{\sum_{k=1}^{N} (1 - V_k)^2}{N}}$$

by penetrating DG value at respective node and rank the sensitivities of all nodes in ascending order to form priority list.

Step 3: Select the bus with top 4 highest priorities.

Step 4: input them into differential evolution function and optimize the capacity of generators at all potential buses using objective function defines in equation 1.

Step 5: Change the size of DG in small steps and calculate power loss for each by running load flow.

Step 6: Store the size of DG that gives minimum loss.

Step 7: Compare the loss with the previous solution. If loss is less than previous solution, store this new solution and Discard previous solution.

Step 8: Repeat Step 4 to Step 7 for all buses in the priority list.

Step 9: Execute the load flow again for the final PVDG values and plot the comparison results.

#### VI. RESULTS AND DISCUSSIONS

In our work IEEE 14 bus system is been considered as a test case to evaluate the feasibility of our proposed work. We have used Newton Rahpson ac load flow analysis to check out the power losses and voltage profile in each bus. Sensitivity index determines the potential buses which are suffering from higher power losses, it reduces the cost and time consumed in placing the PVDG on each bus and to analyze the losses in every case. In our case after locating the top four potential buses which are having higher losses, differential evolution (DE) optimization technique is used to determine the optimal size of PVDG which reduces the losses. The accuracy of evolutionary algorithms depends upon the fact that the objective function must be minimized with number of iterations. In this fitness function value decreases with iterations and fixed to a minimum constant value after 50 iterations. It shows that our optimization objective function is correctly optimized and outcome of this will be as per requirements. Initially the distribution generator size is taken randomly within limits of 0-50 MW for all four potential buses which are later updated as per DE. Since, initially random power inserted by PVDG is considered so when simulation is done each time, different results will be shown. With the introduction of DG the voltage profile has improved which is shown below:



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Table I

Results for Voltage profile before and after DG placement

Bus No	Exist	ing	Present	
	Voltage before Optimization (p.u.)	Voltage after Optimization (p.u.)	Voltage before Optimization	Voltage before Optimization
1	1.06	1.06	1.0600	1.0600
2	1.04	1.04	1.0450	1.0450
3	1.01	1.01	1.0100	1.0100
4	1.01	1.03	1.0132	1.0318
5	1.02	1.03	1.0166	1.0322
6	1.07	1.07	1.0700	1.0700
7	1.06	1.07	1.0457	1.0631
8	1.09	1.09	1.0800	1.0900
9	1.05	1.07	1.0305	1.0520
10	1.05	1.07	1.0299	1.0590
11	1.05	1.07	1.0461	1.0613
12	1.05	1.06	1.0533	1.0540
13	1.05	1.06	1.0466	1.0503
14	1.03	1.07	1.0193	1.0329



Fig. 1. Voltage profile (for Present Work)

After optimal sizing calculation and placement in the IEEE 14 bus system, voltage profile almost at each bus is increased. It reduces because after installation, line losses in the whole system reduce. Since PVDG inserts the active power so a tabular format representation for the active power losses of the system is shown in table 2. Losses in lines connecting all buses are shown in that. It has been compared with the existing work which in performed on IEEE 14 bus system and we found that our voltage profile improvement is better than the existing work.



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#### Table II Losses in the lines between buses in the system

Line	From	То	Active Power Losses	Active Power Losses
No.	Bus	Bus	Before Optimization	After Optimization
1	1	2	4.30	1.49
2	1	5	2.77	1.33
3	2	3	2.33	1.61
4	2	4	1.66	1.02
5	2	5	0.91	0.60
6	3	4	0.39	0.34
7	4	5	0.47	0.24
8	4	7	7.10e-15	0
9	4	9	-3.55e-15	-3.55e-15
10	5	6	0	0
11	6	11	0.12	0.09
12	6	12	0.08	0.07
13	6	13	0.25	0.23
14	7	8	6.93e-16	0
15	7	9	-3.55e-15	0
16	9	10	0.01	0.01
17	9	14	0.08	0.10
18	10	11	0.05	0.04
19	12	13	0.01	0.01
20	13	14	0.11	0.08
			4.30 + 2.77 + 2.33 + 1.66 +	1.49 + 1.33 + 1.61 +
			0.91 + 0.39 + 0.47 + 0.12 +	1.02 + 0.60 + 0.34 +
			0.08 + 0.25 + 0.01 + 0.08 +	0.24 + 0.09 + 0.07 +
			0.05 + 0.01 + 0.11 = <b>13.54</b>	0.23 + 0.01 + 0.10 +
				0.04 + 0.01 + 0.08 =
				7.26

At some lines losses are zero and at others losses are higher than in the optimized case. At some lines the difference is more than 3 MW too. Total losses without PVDG placement is 13.54 MW and after the insertion of generators at required buses it is 7.26 MW. A difference of almost 6 MW is visible, which is a great achievement. In actual sensitivity analysis arrange the losses in all buses in the decreasing order and we have picked the top four bus locations for that. These buses are 2, 3, 4 and 5. Results can be improved if generators are placed on all buses, but it will cost of system tremendously as placement at all buses will include cost of installation, generator and maintenance cost too increases.

Work	Power	% of Loss	
		Reduction	
	Without DG	With DG	
Existing	13.39 (MW)	8.71 (MW)	34.95
Present	13.54 (MW)	7.26 (MW)	46.38



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Fig. 2. Total losses (for Present Work)



Potential buses and PVDG values inserted in the system on those buses



Fig. 2. PVDG capacity placed at 4 higher loss buses

VII. CONCLUSION

This paper deals with that, in order to improve voltage profile and to reduce losses it is necessary to determine the optimal size as well as the location of DG in the system. So we analyze different points which are essential for optimal positioning of DG in our test system with Differential Evolution technique as under:

- 1. Technical losses are considered so that cost of installation and power losses are reduced.
- 2. Loss sensitivity method decreases the requirement to put renewable generators on all buses. It gives the exact buses at which losses are highest and DG can be placed on those buses.
- 3. DE optimization serves the purpose here. Results comparison is done in the form of line losses and improved voltage profile.



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