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A Review on Detection and Monitoring of Stator Faults of Induction Motors

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ABSTRACT: Induction motors are the most widely used electric motors in industry due to their simple structure, stable operation and high efficiency. In particular, induction motors are very important in industry due to their smoothly operation under heavy and variable loading conditions. The maintenance and repair costs increase in unexpected faults in operating conditions. The production capacities of industrial facilities also decline due to the failure of induction motors. Therefore, detection of faults of induction motor is quite important for the industry. Thus, various studies have been conducted to find the most effective technique/s for detection of faults. In this study, the**widely-used** methods to detect and monitor the most common stator faults of induction motors are reviewed. The goal is to determine the most effective and user friendly methods for the end-users or field engineers.

KEYWORDS: Induction motors, Stator faults, Fault diagnosis, Stator monitoring.

I. INTRODUCTION

Induction motors are the most preferred electric motors in the industry due to the ease of speed control, low cost, robustness, and reasonable high efficiency, maintenance and repair costs compared to other motors. Motors faults always have been important since the discovery of electric motors. In the past, only the overcurrent protection, voltage protection, etc. methods have been tried by users to protect the induction motors[1]-[3]. Fault detection and prediction methods can be used especially for large and critical induction motors used in industry. This can prevent any fault and reduce the resultant financial loses. This also reduces maintenance and repair costs. At the same time, it is also possible to prevent the production processes that may occur due to induction motor (IM) faults. If these faults are not correctly monitored and diagnosed, they can lead to reduced efficiency, increased energy costs and further all system shutdown[4]. The importance of early diagnosis of faults of induction motors increases accordingly. Some kinds of faults occurs slowly and the early diagnosis is very critical. The diagnosis and identification of faults may increase the reliability of the systems. Thus, the early diagnosis of fault is essential for the system's reliability[5]. One of the main reason of this is the fact that more than 79% of the electromechanical machines are induction motors [6]. Faults in induction motors often arises specifically in ball bearing, stator – winding and rotor. Namely, 40% of the faults arises from the faults of ball bearing. The same rate for stator-winding faults is about 28% to 36%. The rotor faults are about 10 %[7]-[11]. Even though smart fault diagnosis methods in induction motors are used in the recent years, the conventional systems are still preferred in industry. The most known method is direct observation. This method requires the continuous monitoring and careful control of the operating processes of the motors. Also, equipment including over current relay, phase protection relay, phase sequence relay and residual current circuit breaker may be used in order to protect the motor. Besides, conventional fault diagnosis methods including bearings and gear box oil analysis are preferred in despite of their high-cost and long time-duration [4].

Smart systems are commonly used for fault diagnosis of induction motorsto extract the necessary information without complex mathematical models. Common methods include artificial neural network, genetic algorithms, support vector machine, fuzzy logic, decision-tree and hybrid systems [1], [12], [13]. Each of the motor faults are reviewed below.



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II. STATOR FAULTS

The stator faults of induction motors can be categorized as lamination faults and stator windingfaults. Stator winding faultsoccurdue the failure of insulation in the stator of an induction motor [1]. Stator winding faults lead to high line current in induction motors which increases the operating temperature. The increase in the temperature results failure of stator insulation. Every 10°C increase in tempreature (above the operating temperature) decreases the life of the insulation to half. Stator winding faults may be categorized in five groups including coil-to-coil fault, winding-to-winding fault, phase-to-phase fault, broken connection (open circuit), and coil-to-ground fault (Figure 1).

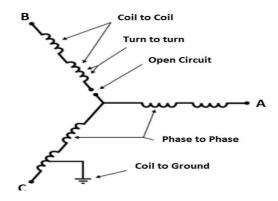


Figure 1. Schematic diagram of the stator faults.

The causes ofstator winding faults may be categorized four groups.

2.1 Thermal

Stators winding faults may arise from thermal aging and thermal overloading. The insulation life decreases to halffor each increase of 10 $^{\circ}$ C in temperature. The effect of the thermal aging may cause the induction motors defenceless to the other factors which cause failure in the insulation structure. If the insulation system loses its physical integrity, it cannot resist to dielectric, mechanical and environmental effects. The effect of the temperature on thermal aging can be minimized by decreasing the operating temperature or using high-quality insulation material. Thermal overload may appear depending on the applied voltage[5], [14].

2.2 Electrical

Electrical causes of stator winding faults may include dielectric, insulation, corona and temporary voltage rise. The relationship between the insulation life and the effects of the voltage applied to insulation materials should be taken into consideration during the selection of the materials and establishment of the coil design. The electrical stator faults can be categorized asshort circuit between phase-to -phase short-circuit, winding-to-windingand ground-to-winding. In an insulation system with over-voltage (higher than the critical voltage) corona and localised discharge may appear. The winding insulation failure may also originate from corrosion and chemical reactions. Transient voltage conditionsare another cause of stator winding failure which shortens the life of the winding and leads to failures.

2.3 Mechanical

The rotation of rotor or fan which may touch to the stator windings can be considered the main sources of mechanical faults of stator winding faults. The stator current also induce mechanical forces on the stator windings which may lead to winding failures. The cooling-fan of the motor may touch stator windings as a result of bearing failures, shaft deflections, and misalignment. If the cooling-fan touch the stator during the start-up it may cause in lamination



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damage. This may results in ground faults. On the other hand, if the cooling-fantouch the stator during the full-speed operation of the motor, it may cause over-heating and ground faults. Furthermore, faults may appear due the loose fan blades or any object which may move into the motor via ventilation system [9].

2.4 Environmental

Humidity, presence of chemicals, environmental temperature-rise and ventilation problems etc. may cause stator failures of induction motors. Therefore failures due to environmental factors can be reduced by identifying their presence the work area. The increase in the environmental temperaturedamages the insulation of and failure in windings may occur accordingly. Besides, short-circuit problems originated fromhumidity may cause important faults in the motors. Depending on the failures in the stator of the induction motors, over-current and mechanical vibration may appear. Over current may increase the temperature and the windings may burn if the motor is notprotected against over-temperature[2], [13].

III.MONITORING METHODS OF STATOR FAULTS

Monitoring of induction motors is very important in order to diagnose faults and prevent the possible failures. In the recent years, various many studies carried out on effective condition monitoring and fault diagnosis methods according to their common presence in the industrial processes[5].Common methods used in order tomonitor and identify the failures in induction motors are grouped under five categories.

3.1 Sound and Vibration Analysis

Loose stator windings, variable air gap, voltage unbalance may lead to vibration in induction motors[4], [6]. The resonance between electromagnetic force and stator is the main cause of the noise in the induction motors. Glowaczet al. [15] diagnosed the in stator windingfaults by using acoustic signal. This study was done for single phase induction motor. The success rate was 88% in the study. Arrendondo et al. [16] worked on the diagnosis of induction motor faults by using sound and vibration signals. They used complete ensemble empirical mode decomposition (CEEMD) method in this study. Ayaz et al. [17] detected insulation failure of winding of induction motors by using current and vibration signals. The study established a relationship between motor current and vibrations via coherency. Therefore this property is evaluated as an indicator of the stator insulation faults.

3.2 Air Gap Torque Analysis

Air gap torque appeared during the start-up of the induction motors is sensitive to the unbalanced in supply voltage, cracked rotor bars or asymmetrical stator windings[18]. When the motor is subject to an unbalanced supply voltage harmonics appear in the air gap torque [19]. The eccentricity in the air gap causes fluctuating torque, unbalanced magnetic flux and reduces the power factor. This causes speed pulsations, vibration, acoustic noise, bearing and rotor damage. This may cause deterioration in conductors and insulation[20]. Filhoet al.[21] used magnetic flux and vibration signals of induction motors to monitor and diagnose stator faults. They found that short-circuit faults windings can be diagnosed by using magnetic flux and vibration signals.

3.3Current Analysis

Induction motor faults mainly reflects into the stator current as harmonics. The analysis of stator current is mainly known as current signature analysis method (MCSASince stator current is always available when the motor is running it is easier to perform current signature analysis than other methods. Thereforethis method is often preferred because of its convenience. However, load factor of motor and the signal to noise ratio affect the accuracy of this method. [5], [18].

Lee et al. [22] used stator current information to detect induction motor faults. In this study, the most reliable phase current among 3-phase current information was selected by fuzzy entropy method. It was then trained with artificial neural networks. The faults were investigated by Fourier and wavelet transforms and classified into six categories.Jimenez et al. [23] have offered an online method to identify faults of induction motors. In this method, steady state stator current and axial flux signal analysis information is used. In order to improve the accuracy



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thesignal is subjected to Hilbert transformation and wavelet analysis, respectively. Then, error thresholds were determined by statistical analysis. Thusthe faults which may be at the initial stage are detected successfully. Allal and Chatete have suggested an approach called Park Vector Product Approach (PVPA) for cases where rotor or stator faults exist. In this study, the classical methods such as motor current signature analysis (MCSA) are compared with recent methods such as motor square current signature analysis, Park's vector square modules, Park-Hilbert techniques [24].

3.4 Temperature

Overheating in an induction motor is also considered as one of the main causes of a fault [25]. The industry usually uses equipment such as fuses, thermal magnetic switches and overcurrent relays for thermal protection purposes. However, these devices cannot provide complete protection. [26]. Stator failure detection of an induction motor is normally performed by measuring the temperature change of the motor [14]. Temperature is observed through sensors installed on the motor[26]. The detection of stator fault by analysis of temperature is based on stator resistance and thermal models. Other factors such as ambient temperature and cooling should be considered in these models[5]. Rajagopal et al. [27]studied a two-dimensional transient analysis method by using heat transfer coefficients of an induction motor. Transient thermal behaviour study is useful for determining the causes of failure in induction machines.Glowacz and Glowacz have studied thermal imageanalysis for fault diagnosis in a single-phase induction motor. Thermal images are analysed by a method called MoASoS (Method of Area Selection of States). In this method, MoASoS and an image histogram were used to construct feature vectors. The classification of the obtained vectors was performed with NN (Nearest NeighbourClassification) and Gaussian Karma Models (GMM)[28]. Baneira et al. [29] have proposed a method based on dc signal injection for stator winding temperature estimation in dual three-phase induction motors. Thethe proposed methods is verified experimentally.In another study, Ramirez et al. [30] have proposed a method based on thermographic image segmentation for fault detection of induction motors. This method is also based on the repercussion of errors along the kinematic chain.

3.5 Magnetic Flux

The air gap flux changes sinusoidally if an induction motor operates under normal conditions. Howeverstator faults can cause changes in air gap flux distribution. Depending on the stator faults, any deterioration in the air gap flux density will create an axial homopolar flux. This flux flows along a shaftwhich can be detected by a search coil installed around the shaft. It is better to detect signal variations using an external flux detection sensors. The air gap flux can also be detected by sensing the voltage in two uniformly positioned motor windings[5], [18]. The flux signal is analysed by various methods to extract the required information as indicator of stator faults of induction motors.

IV. CONCLUSION

In this study, common stator faultsof induction motors and detection methods have been reviewed. Monitoring and diagnostic methods have also been discussed briefly. The study summaries the most effective and user friendly methods for the end-users or field engineers. The study also provide a list of recent publications on the stator faults of induction motors for the interested researchers who may be interested in certain methods.

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