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Survey towards Find it Pro: A WIFI Object Tracker

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ABSTRACT: Humans are complex entity. Many times, they forget little simple things. One of such things is loose objects in nearby place. People might forget the keys where they have kept or remote to the TV in the very same room. People spend an enormous amount of time and effort looking for lost objects. To help remind people of the location of lost objects, various computational systems that provide information on their locations have been developed. We propose novel method to use IoT to search and detect these small objects in limited area. The objects are detected through use of microchip and the user gets reply through buzzer or led lights to locate these objects. The system helps to save time and ease mind after the objects are found. On large scale the idea can utilized in warehouse to detect the specific racks. In pharma the same idea can be used to detect the specific box of medicines.

KEYWORDS: microcontroller, IoT, ESP2866, Android Application, Loss of objects, Satisfaction

I. INTRODUCTION

Technology has helped humans to improve their lifestyle to a very great extent. Automation of things through IoT has improved every aspect of lifestyle from ordering things online to washing clothes through machine. The longevity of food is increased by refrigerators and the entertainment is brought to doorstep with help of television. Everything is created by human and for human and but again humans are complex entity. Many times, they forget little simple things. One of such things is loose objects in nearby place. They might forget the keys where they have kept or remote to the TV in the very same room. The objects are in front of them but due to some reason at that very moment they are not to find it. This increases the anxiety as well loss of patience to find the thing. Humans spend an enormous amount of time and effort looking for lost objects. To help remind them of the location of lost objects, various computational systems that provide information on their locations have been developed in recent years. The existing research factor for same is working in image processing where the person hangs the camera in his neck and captures view of whole room to find the lost objects. However, prior systems for assisting people in finding objects require users to register the target objects in advance. This requirement imposes a cumbersome burden on the users, and the system cannot help remind them of unexpectedly lost objects.

We propose novel method to use IoT to search and detect these small objects in limited area. The objects are detected through use of microchip and the user gets reply through buzzer or led lights to locate these objects. The system helps to save time and ease mind after the objects are found. On large scale the idea can utilized in warehouse to detect the specific racks. In pharma the same idea can be used to detect the specific box of medicines., etc.

Paper is organized as follows. Section I gives the introduction topic with need for system and overall use over world. Section II gives the related work till now in this field for the system. Section III gives the architecture for the system and inclination of more facilities included in the system. Finally, Section V presents conclusion. Finally, Section V presents conclusion.

II. RELATED WORK

2.1 Computational Systems for Finding Lost Objects

The Various types of sensors, such as wireless tags ,Bluetooth, stationary cameras, and wearable cameras, have been studied for systems to assist users in finding lost objects. Active and passive radio-frequency identification (RFID) tags are frequently deployed by attaching them to target objects. While RFID tags are effective in indoor environments, they cannot locate an object when taken outside the search range. To expend the search range, a combination of Bluetooth and GNSS are adopted in some commercial products . Although these systems can provide the angle and distance from the tag, their guidance is less intuitive and attaching an external tag to each object will be a major bottleneck to track a large number of objects. Alternatively, camera-based systems have the merit of not requiring external sensors attached to objects.However, stationary cameras do not solve the problem of the search range and are weak against occlusions when objects are hidden by other entities. Wearable camera-based systems mitigates these problems by capturing images from the user’s viewpoint. Since the camera moves along with the user, the system captures a close-up of the surrounding environments and it can be carried, significantly expanding the search range. The system consists of head-mounted RGB and infrared cameras for capturing pre-registered objects. It assists in object search by showing the last scene of the target object detected. The same strategy is adopted in this work

2.2 Camera-based systems for Mitigating Memory Problem

Camera-based systems are used for mitigating memory problems other than losing objects since visual information offers a large amount of information better than textual information [5]. Hodges et al. [13] proposed a wearable camera based system called SenseCam, which takes wide-angle pictures periodically (e.g., one shot every 30 s) to remind users of past events. Li et al. [9] proposed FMT, a wearable memory-assistance system to remember the state of objects (e.g., the last time the plant was watered). While their hardware configuration is similar to ours in using neck-mounted wearable cameras, they aim to recall past interactions of a few numbers of daily-used objects, asking users to attach AR markers to each object. In contrast, GO-Finder aims to expand the range of objects which could be searched for by removing the registration operation

2.3 Objects and Hands in First-Person

Videos GO-Finder executes hand-held-object detection and grouping to discover objects appearing in first-person videos. Discovering objects in first-person videos is a difficult problem since object categories appearing in daily life are massive, diverse, and individualdependent. To this end, various methods have been proposed to discover objects in first-person videos [1, 3]. Lee et al. [6] developed a model to discover important object regions using multiple first-person saliency cues. Lu et al. [10] proposed an object clustering-based method for personal-object discovery. Their system involves object-scene distribution based on the assumption that personal objects appear in different scenes while non-personal objects typically remain in similar scenes. Since objects appearing in first-person videos are typically handled by hands, hand information is used to improve object detection. Lee et al. [7] proposed using hands as a guide to identify an object of interest from a photo taken by people with visual impairment. Shan et al. [12] collected a large-scale dataset of hand-object interaction along with annotated bounding boxes of hands and objects in contact with each other. Their proposed system can detect hands and objects in contact with each other from an image. Our aim is not only detecting hand-held objects but also to discover hand-held-object instances from first-person videos, which reduces the number of candidates to be registered.

III. METHODOLOGY

We propose novel method to use IoT to search and detect these small objects in limited area. The objects are detected through use of microchip and the user gets reply through buzzer or led lights to locate these objects. The system helps to save time and ease mind after the objects are found.

The Proposed System:

- └ The system is totally dependent on IoT.
- └ The objects are tagged with ESP8266
- └ The objects have separate buzzer and Led to Specify their Position.

- L The system can be operated through smart phone.
- L The system has separate controller device to control specific object.

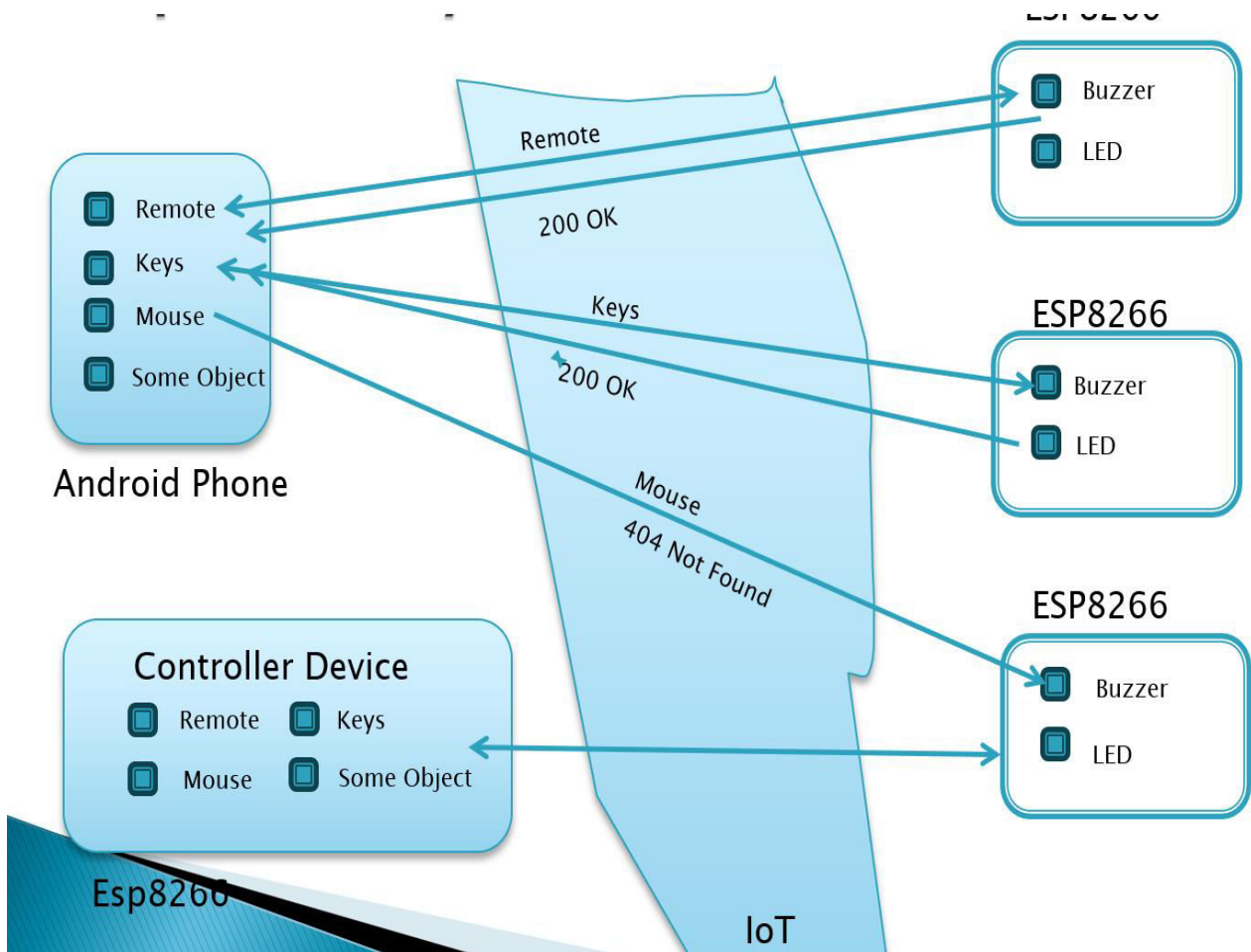


Fig 1: System Architecture

IV. CONCLUSION

We have surveyed for the system through the existing system of camera based and handheld devices. In the system the object is searched in specific area where the system is setup. The minimum distance is evaluated. The object is detected by buzzer sound or Led flashing. The range for finding lost objects can be increased.

The same prototype can be used for searching physical things in big entities like medicine in medicine warehouse. Etc.

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